SIMulation of new manufacturing PROcesses for Composite Structures (SIMPROCS)

Jonathan Belnoue, Adam Thompson, Xiaochuan (Ric) Sun, Iryna Tretiak, Kate Gongadze, Yi Wang, Anatoly Koptelov, Sarthak Mahapatra, Maria Onoufriou, Jordan Jones, Bassam El Saied, Byung Chul (Eric) Kim, James Kratz, Dmitry Ivanov and Stephen Hallett

Composites manufacturing simulation is a strong activity in the Bristol Composites Institute. Our activities range from material characterisation, to novel mathematical formulations, software development and industrial applications. Over the last 5 years, the main vehicle for these activities has been the EPSRC SIMPROCS platform grant.

Constitutive modelling of prepreg

Our Defect Generation Mechanisms in Thick and Variable Thickness Composite Parts: Understanding, Predicting and Mitigation - DefGen project started the development of numerical tools to predict the generation of consolidation-induced prepreg defects in 2014. Following further investments from the EPSRC (SIMPROCS), the National Composite Centre (Technology Pull-through project and DETI program) and Rolls-Royce (sponsorship of an EngD studentship), the technology has now matured to the point where we can simulate the autoclave moulding of industry-sized components with ply resolution in under an hour. The earlier ply-by-ply version of these tools are distributed for free from Bristol Composite Institute Github page.
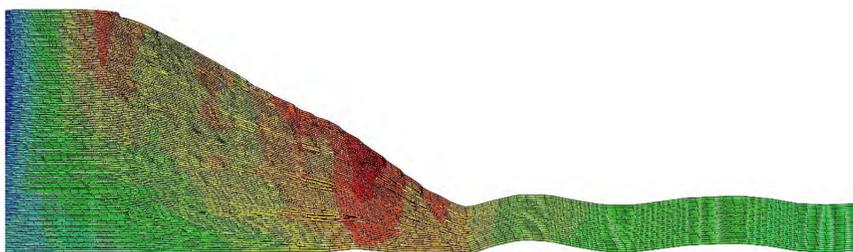

Figure 1: Prediction of consolidation-induced fibre path defect in severely tapered laminate.

Modelling of Textiles

Developing process modelling capability for textile composites is a core part of our research. Our focus has been on generating methods to predict the deformation of textiles at different length scales to inform both manufacturing and design. We have developed tools to predict deformations arising from forming and compaction, able to accurately predict the occurrence of defects. This capability is available via our BCI github. Alongside this we have developed advance modelling approaches to accurately predict the internal architecture of complex woven preforms. Our current focus is on developing a new solver, SimTex, which has been specifically formulated for process modelling, to produce highly accurate yet uniquely fast predictions.

Shear angle (rad)
0.54
-0.52

Figure 2: Prediction of manufacturing-induced deformation of textiles: mesoscale modelling of fabric forming (left) and microscale modelling of complex woven T-section (right).

Working with industry

Beyond the healthy pool for industrial partners who supported the project and attended quarterly review meetings to help steering the project direction, we have also supported industry one to one. For example, we worked with BAE systems in coupling in-situ sensing and real-time thickness predictions to gain greater control on part dimensional tolerance (see Figure 3). This piece of work was funded through an EPSRC Impact Acceleration (IAA). IAA funding was also used to raise the TRL level of our textile simulation tools (see Figure 2 - right).
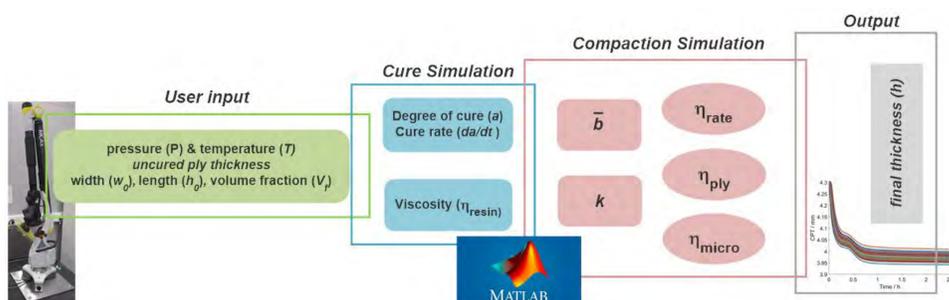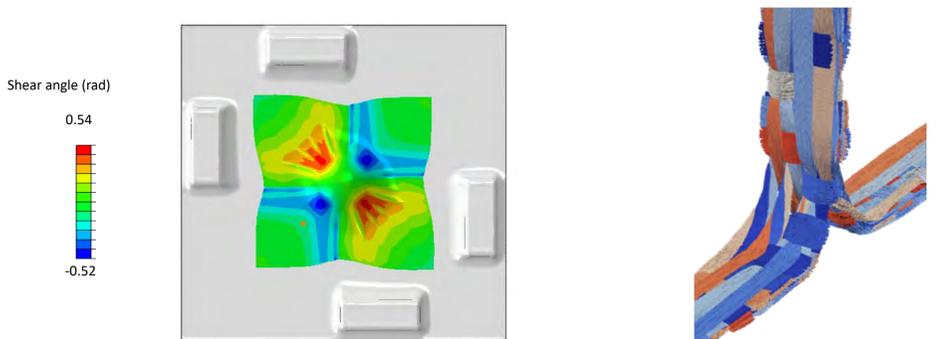
International collaborations

The grant was also used to raise the group international profile. Our researchers have visited leading international centres such as the Ecole Centrale de Nantes and Technical University of Munich. We have welcomed visitors to come and work with us on process modelling, accessing our tools, techniques and software to create new capability, with many successful collaborations to date. A good example is the visit of PhD student Armin Rashidi from the University of British Columbia, Canada, who developed a user contact subroutine combining UBC's friction model with our compliant contact approach and the 1D version of our compaction models, to simulate forming and consolidation induced defects in textile prepregs.
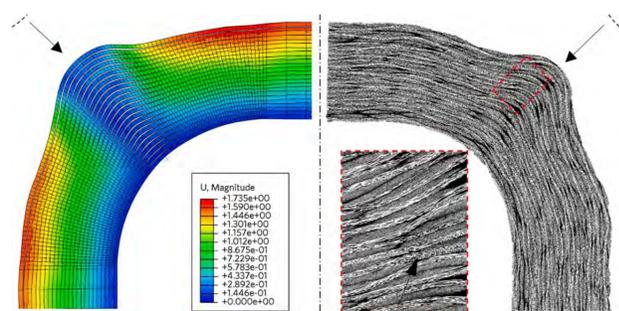

Figure 3: Together with BAE Systems we demonstrated the feasibility of using in-situ measurements with our 1D compaction models for tighter part dimensional tolerance control.

Figure 4: Experimental validation of consolidation-induced defects in woven prepreg laminates. This work was done in collaboration with the University of British Columbia.

Composites: Made Faster
Rapid, physics-based simulation tools for composite manufacture

Adam Thompson, Ekaterina Gongadze, Matthew Edwards, Laurence Kedward, Michael Pei, Yi Wang, Lachlan Williams, Siyuan Chen, Jonathan Belnoue, Tim Dodwell (University of Exeter), Stephen Hallett

Process simulation is a powerful tool to help mitigate part variability and reduce over-design of composite components. A major challenge in achieving good simulations is to consider the variability, inherent to both the material and the manufacturing processes, so that the statistical spread of possible outcomes is considered rather than a single deterministic result. This project aims to achieve this by developing a probabilistic modelling framework based on rapid numerical tools for modelling each step in the composite manufacturing process.
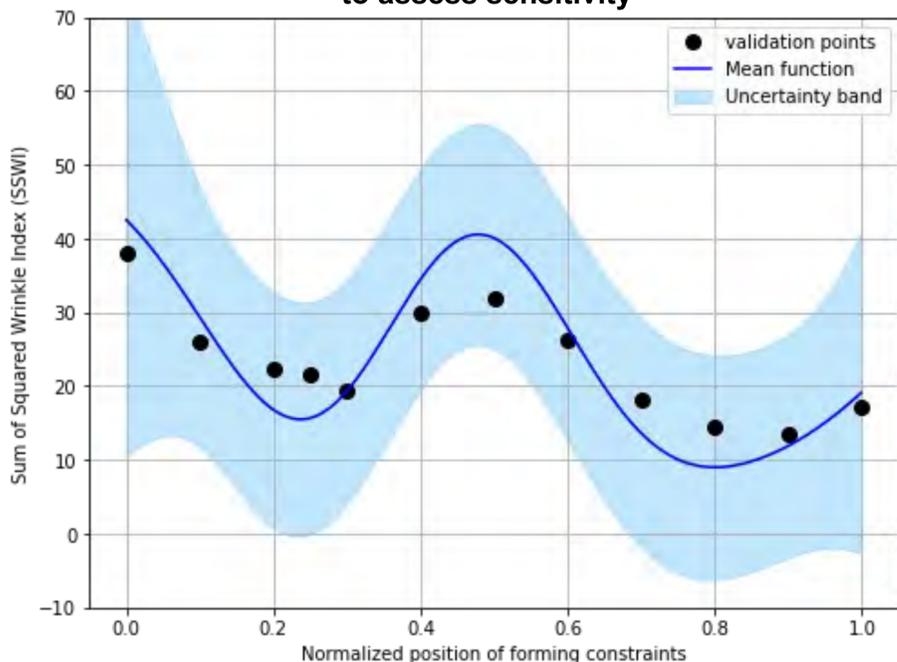
Prediction of internal architecture of 3D orthogonal weave
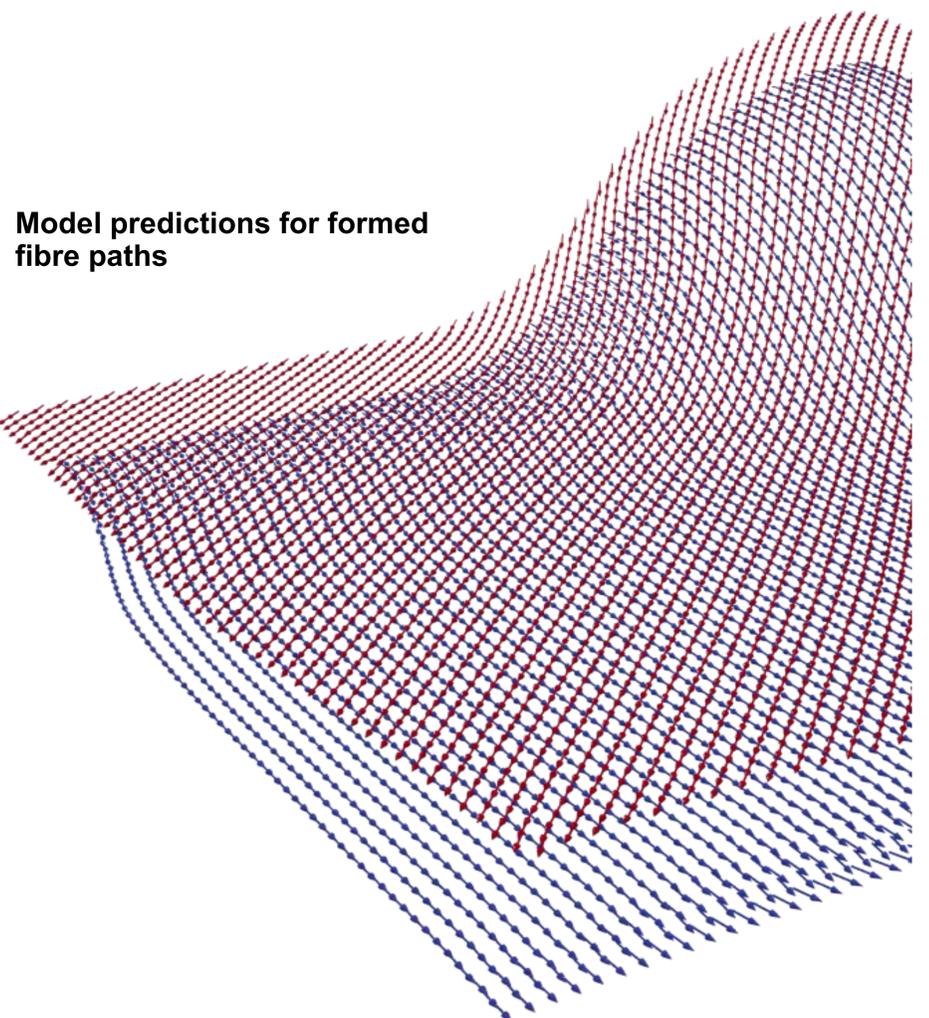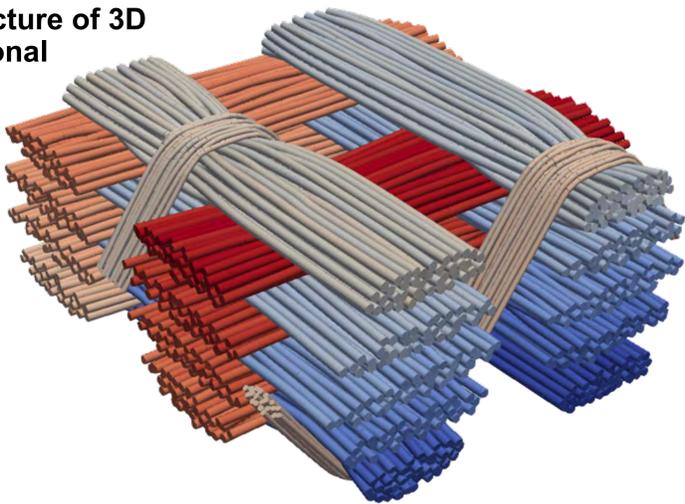
Model predictions for formed fibre paths

Focusing specifically on textile composites, this project will develop a new bespoke solver, with methods to simulate preform creation, preform deposition and finally, preform compaction, three key steps in composite manufacturing. Aided by new and developing processor architecture, this bespoke solver will deliver a uniquely fast, yet accurate simulation capability.

Gaussian Process Emulator built from physical model to assess sensitivity

Sum of Squared Wrinkle Index (SSWI) vs Normalized position of forming constraints

- validation points
- Mean function
- Uncertainty band

The methods developed for each process will be interrogated through systematic probabilistic sensitivity analyses to reduce their complexity while retaining predictive capability. This will ultimately provide a tool that is numerically efficient enough to run sufficient iterations to capture the significant stochastic variation present in textile composite manufacture processes, even at large scale. This will enable a step change in manufacturing engineer's ability to reach an acceptable solution with significantly fewer trials, less waste and faster time to market, contributing to the digital revolution that is now taking place across the industry.

Kinematically enhanced modelling for fast simulation of composites processing

Jonathan Belnoue and Stephen Hallett

Earlier work carried out at BCI has shown the possibility to accurately predict consolidation-driven defect formation in composite parts using a ply-by-ply approach (see Figure 1). However, using this method, a typical model for a lab-scale specimen can easily reach the hundreds of thousands of degrees of freedom, which makes it unsuitable for the modelling of full-scale components and limits its applicability for the modelling of real industrial cases. Recent efforts have allowed to overcome this difficulty using kinematically enhanced constitutive modelling for layered structures made of soft anisotropic material. The proposed framework is able to significantly reduce the computational cost of the simulation. The scheme allows the modelling of larger components.
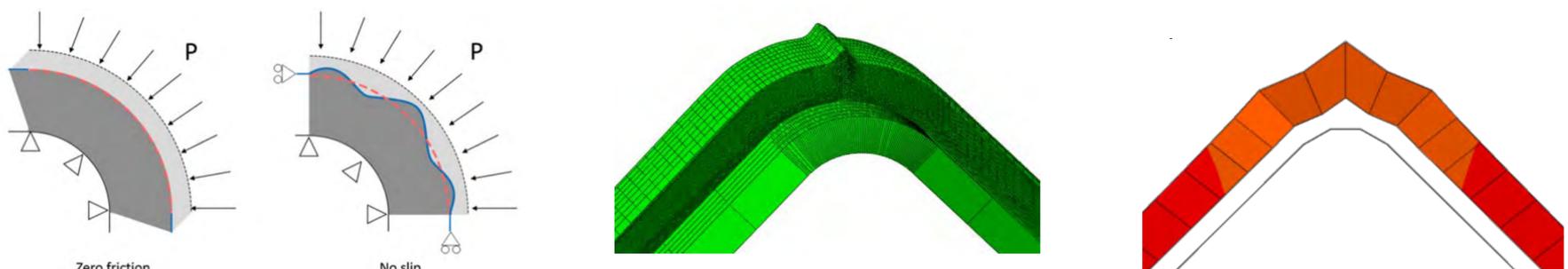

Zero friction   No slip

Figure 1

Homogenisation scheme

The behaviour of each ply constituent of the structure follows BCI's model for prepreg under processing conditions. The interactions between the plies are explicitly modelled as thin extra layers of pure fluid. As illustrated in figure 2, 2 layers inside the stack can be homogenized using a combination of: a volumetric averaging of the strains, the compatibility condition at the plane where the 2 volumes join and the Hill-Mandell condition. This allows linking the macroscale apparent behaviour of the stack to the responses of the materials it is made of. Once 2 plies have been homogenised, the homogenised block can be homogneised with another layer and the whole laminate can be build by successive homogeneisation of 2 layers.
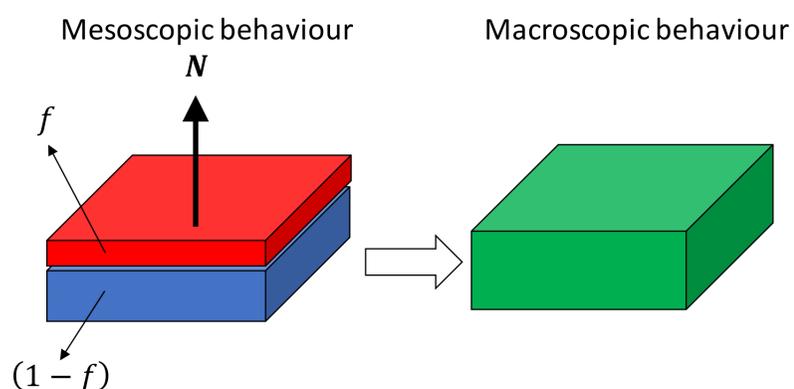
Mesoscopic behaviour   Macroscopic behaviour

N
f
$(1-f)$

Figure 2

Speed Improvement

The number of degrees of freedom seen by the solver is drastically reduced. Additional reduction of the runtime is obtained through the fact that highly strained regions are smeared-out within the laminate homogeneous response thus easing the convergence of the FE scheme. In the case of a lab-scale L-bend specimen in Figure 1, the runtime has been taken down to 30 mins from 3 days for the ply-by-ply. Figure 3 shows a more complex specimen, where the time improvements are even more significant.
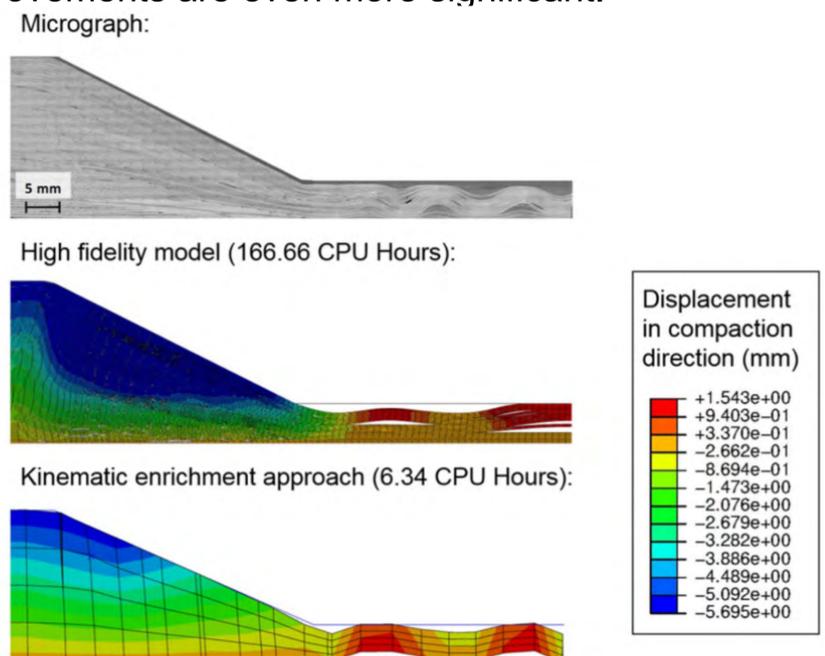
Micrograph:

5 mm

High fidelity model (166.66 CPU Hours):

Kinematic enrichment approach (6.34 CPU Hours):

Displacement in compaction direction (mm)
+1.543e+00
+9.403e-01
+3.370e-01
-2.662e-01
-8.694e-01
-1.473e+00
-2.076e+00
-2.679e+00
-3.282e+00
-3.886e+00
-4.489e+00
-5.092e+00
-5.695e+00

Figure 3

Reference: Belnoue, J.P.H. and Hallett, S.R., 2020. A rapid multi-scale design tool for the prediction of wrinkle defect formation in composite components. Materials & Design, 187:108388.

Model-based Optimisation of Automated Fibre Placement (AFP) Deposition

Jonathan Belnoue, Yi Wang, Sarthak Mahapatra, Dmitry Ivanov and Stephen Hallett

AFP is the most widespread automated deposition technique for composites in industry. Although the method has been around for over 40 years and works well for relatively simple geometries (i.e., low level of double curvature), setting up machine parameters in order to avoid defects remains challenging. Current industry practices rely largely on time-consuming, costly and wasteful physical trials. The SIMPROCS team has recently developed simulation tools that would allow to do most this work virtually on a computer.

Industrial challenge

A commercial AFP machine is built from a computer numerically controlled support robot (gantry in Figure 1) that controls the layup path and speed and a deposition head controlling feeding, cutting and compaction of the incoming material. As illustrated in Figure 2, one of the main obstacles to wider uptake of AFP is the difficulty to produce preforms of sufficient quality when tapes are deposited along curved paths or on complex doubly-curved surfaces.
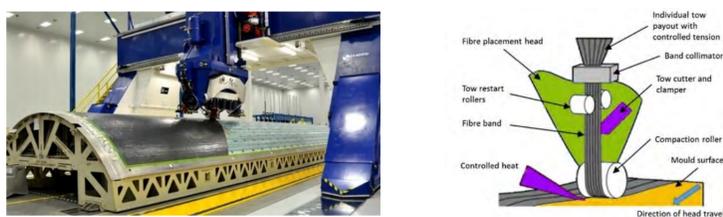

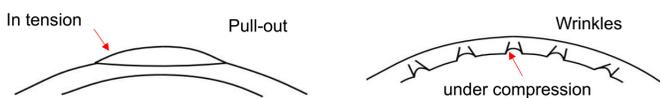**Figure 1:** An AFP machine (left) and schematic of an AFP head (right).

Figure 2: Steering-induced tape pull-out and wrinkles are difficult to avoid in AFP deposition.

Virtual AFP platform

An essential part of the virtual AFP platform developed in this project has been the development of bespoke material characterisation techniques and models able to capture how the mechanical behaviour of prepreg tapes evolves with temperature, pressure and deformation rate.

Figure 3: Overall framework of the AFP virtual platform.

Virtual AFP platform validation

The virtual AFP platform was validated by comparing its predictions with real-life AFP data from the open literature [1]. The same material and deposition conditions were considered in the model and in the experiments.
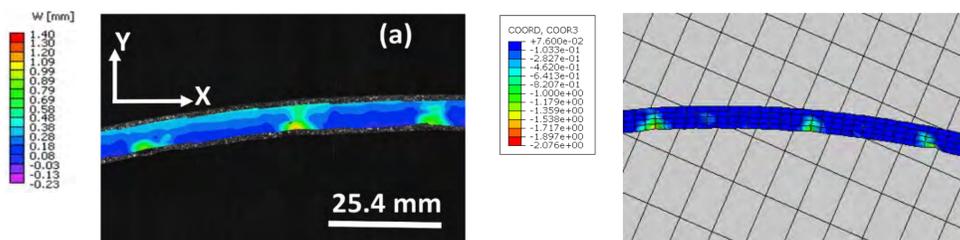

Figure 4: Out-of-plane deformation map of the AFP with a steering radius ρ=305mm. Experimental measurements from [1] (left) match our predictions (right) very well.

Model-based process optimisation

The developed platform is the only AFP simulation capability worldwide that can account for the effect of process parameters and allow optimisation of the deposition conditions.
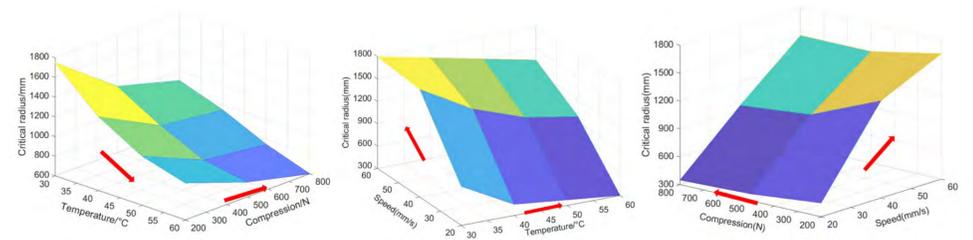
Figure 5: Predictions for the evolution of the critical steering radius (i.e., minimum radius that can be deposited without the formation of a wrinkle) with deposition conditions.

Current developments and Future activities

In another EPSRC-funded project (i.e., Composites: Made Faster - EP/V039210/1) on real-time simulations and optimisation of textile forming, the group is developing Bayesian optimisation methods. These could be directly used to find the optimum deposition conditions in the context described here. Ongoing work is looking at improving run times through adaptive re-meshing and homogenisation of the plies already deposited. Early results are very promising with runtimes for the deposition of one tape being as low as 20 minutes (see Figure 6).
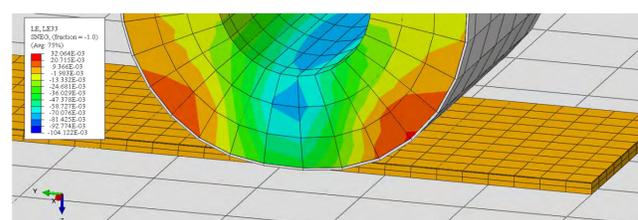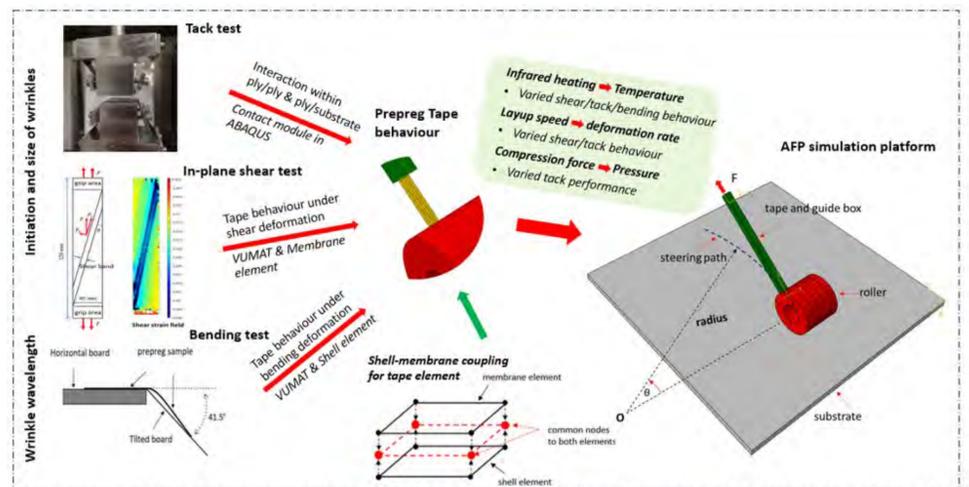

Figure 6: Homogenisation of the plies already deposited allow taking the runtime of the simulations below 30 mins.

[1] Rajan S, Sutton MA, Wehbe R, Tatting B, Gürdal Z, Kidane A, et al. Experimental investigation of prepreg slit tape wrinkling during automated fiber placement process using StereoDIC. Compos Part B Eng 2019;160:546–57. https://doi.org/10.1016/j.compositesb.2018.12.017.

Deep learning approach for predicting the architecture of 3D textile fabrics

Anatoly Koptelov, Bassam El Said, Adam Thompson, Stephen Hallett

The idea of the proposed system is to capture the features of fabric's deformation process by learning yarns' behaviour from a set of test simulations. The proposed tool for this task is a complex system of convolutional and long short-term memory neural networks. The network facilitates the extraction of relevant features from a deformed yarns' geometry and learns characteristic patterns in evolution of these features throughout the deformation process. The trained network is able to mimic fabric's behaviour and to predict further stages of compaction without employing time-consuming textile solvers.

Time-distributed solution

Weaving simulations are performed within a number of consecutive timesteps. It is important to be able to predict the mechanical properties of the woven fabric based on its initial geometry and architecture

Step 1
Initial architecture

Step 4,
Intermediate step

Step 20
compacted architecture
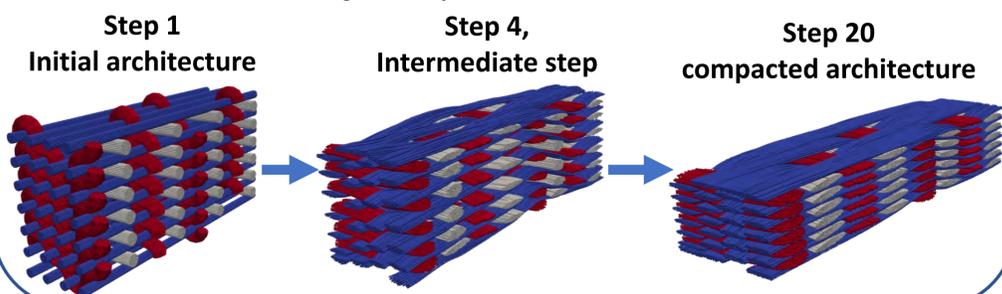
From kinematic to FE model

Kinematic geometry is converted into a voxel grid, where each voxel stores information about fibre volume fraction and fibre orientation. Voxel grid is then transferred into FE model.
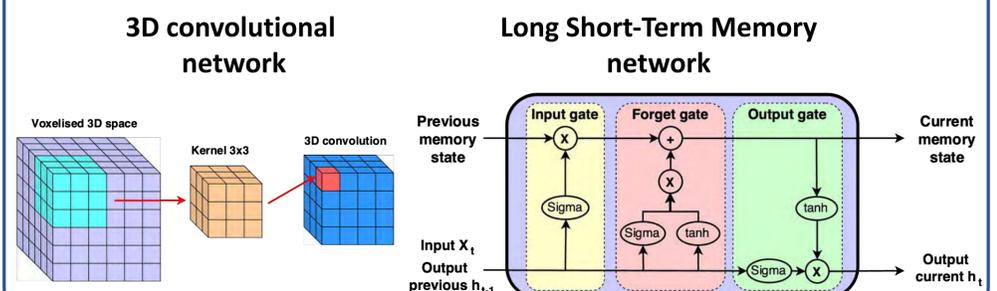
Kinematic model

Voxel model

Voxel model (no matrix)
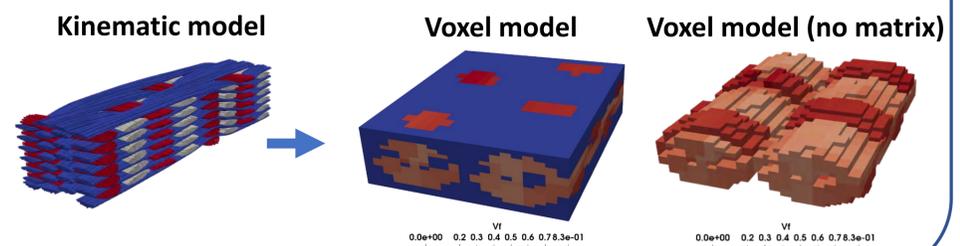
Generating training set

4000 weaving architectures with different yarn paths were generated for further neural network training.
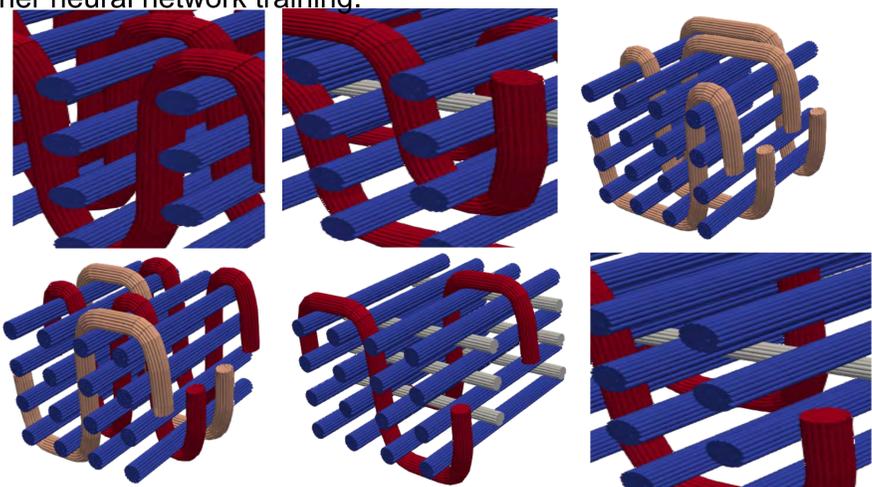
Learning deformation patterns

A combination of convolutional and recurrent neural networks was considered to extract relevant features and to learn their evolution throughout deformation process

3D convolutional network

Voxelised 3D space — Kernel 3x3 — 3D convolution

Long Short-Term Memory network

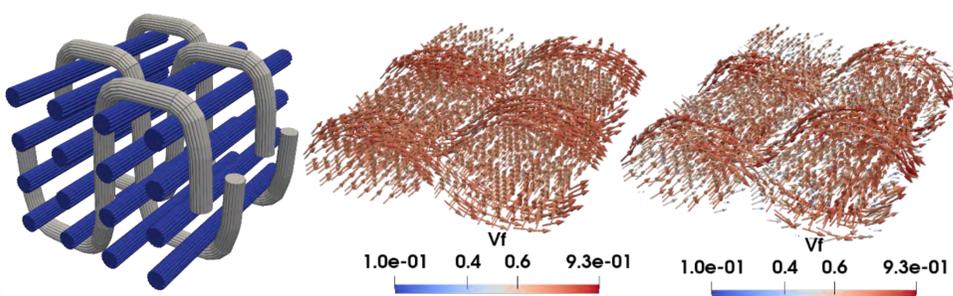## Predicted woven architecture for voxel models

The comparison between compacted textile structure (ground truth) and AI prediction is shown below. Colour represents fibre volume fraction.

Case study 1

Kinematic model, initial architecture

Compacted voxelised model, ground truth

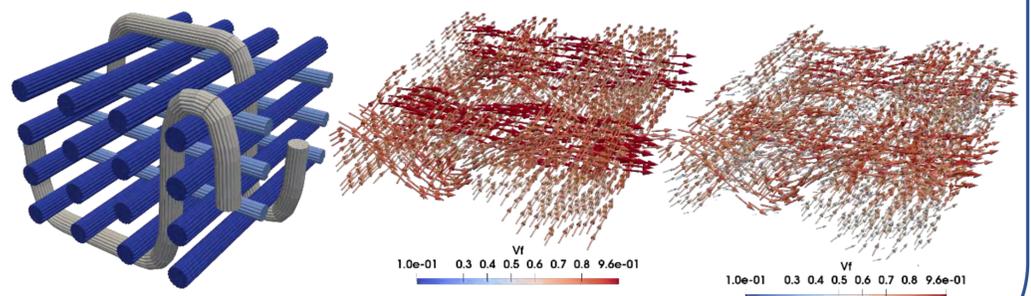**Compacted voxelised model, AI prediction**

Case study 2

Kinematic model, initial architecture

**Compacted voxelised model, ground truth**

**Compacted voxelised model, AI prediction**

SimTex: a high-fidelity modelling tool for technical textiles

Adam Thompson, Jordan Jones, Matt Edwards, Ric Sun, Stephen Hallett

SimTex is a bespoke solver initially developed to generate virtual models of textiles, accurately predicting deformations to tow paths and cross sections. Through the use of efficient contact detection algorithms and unique boundary conditions, SimTex is able to model highly complex and non-periodic textiles, providing the ability to analyse their internal architecture at a whole new level of detail.
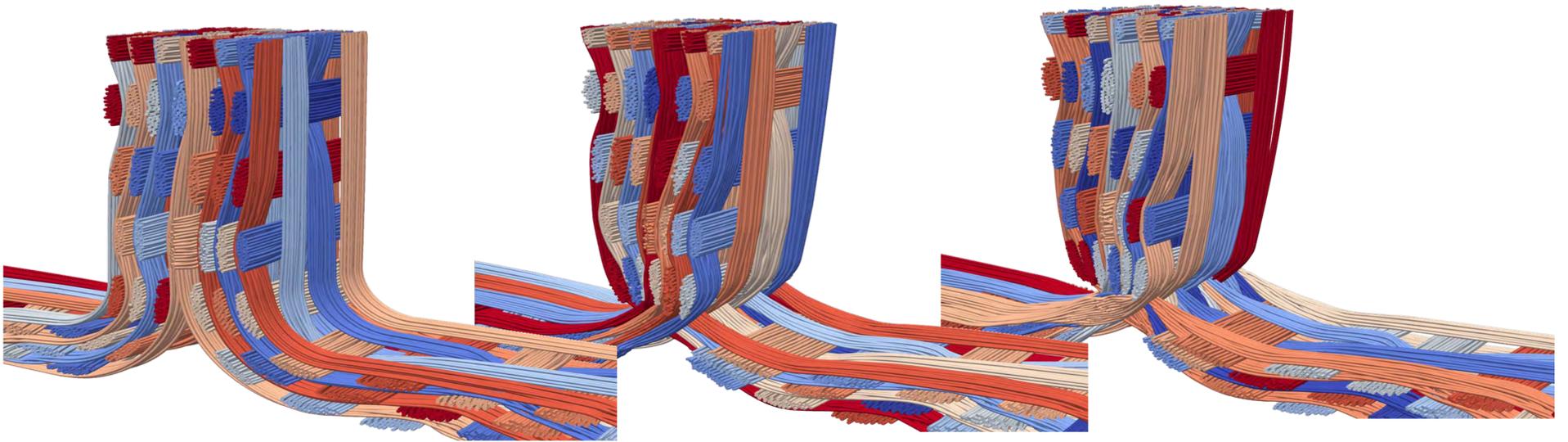
Using basic weave design information, SimTex constructs an initially simple representation of the weave architecture. The tows are represented by multiple chains of truss elements, each chain considered to be a virtual fibre. The virtual fibres within a single tow are interpenetrating in their initial configuration. Through the introduction of contact models, the virtual fibres are pushed out of contact, while under tension, until the structure equilibrates thus creating a hyper realistic virtual model of the textile.
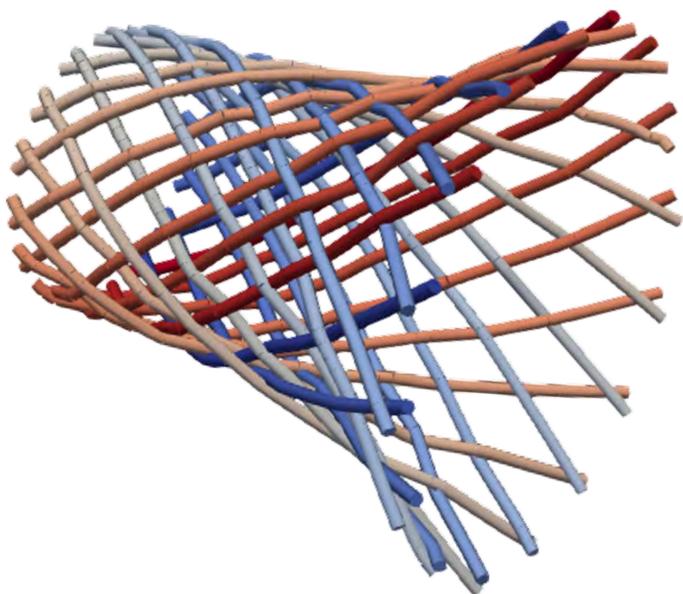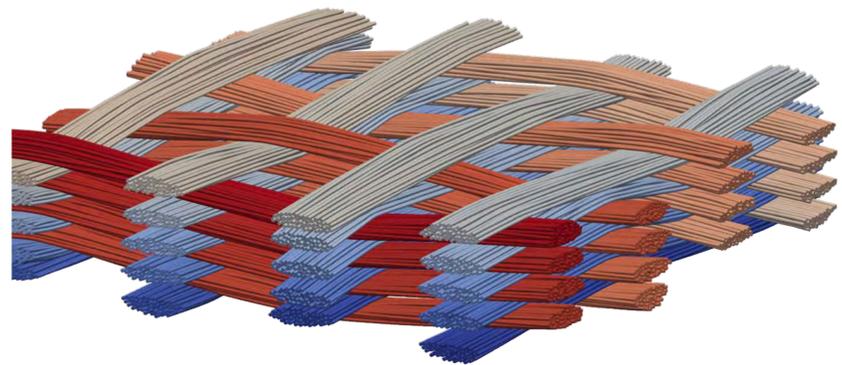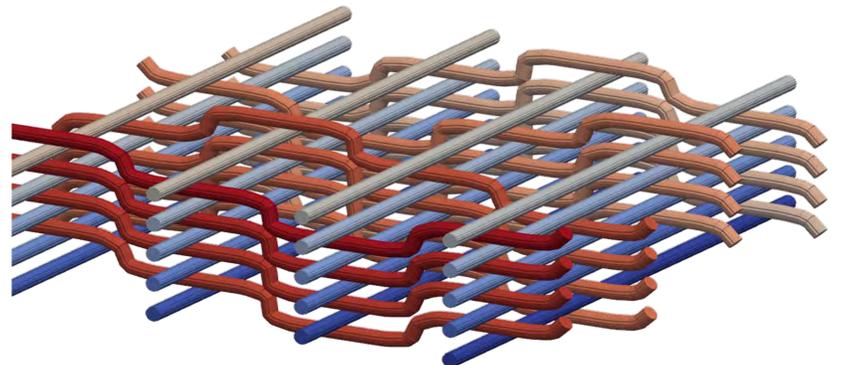
Originally developed to create unit cell models of 3D woven textiles, it has evolved to construct complex near net shape preforms with bifurcations and tapering, as well to explicitly model textile processes, such as braiding, with the introduction of novel features such as the 'Virtual Bobbin'

A fully automated framework for composites structure mould design optimisation
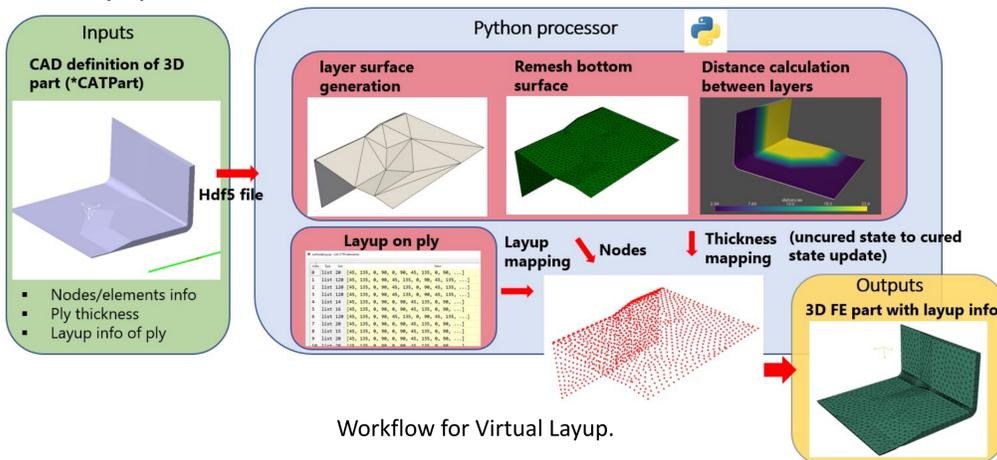
Yi Wang, Jonathan Belnoue, Stephen Hallett

The mould tool is a critical part in composite structure manufacturing, largely determining the structure's quality, particularly for dimensional tolerance and consolidation-induced defects. Meanwhile, it is a very expensive single part, and too costly to modify once made and full-scale part production begun. In this work, a fully automated framework for the prediction of thickness and consolidation-induced defects in composite parts manufactured by autoclave moulding was delivered. A physical demonstrator with industrial complexity was used to assess the accuracy of framework and manufactured for validation. The comparison between the part quality predicted by the software tool and the quality of the manufactured demonstrator showed good agreement. Further, an automated tool allowing for optimization of the tooling for increased part quality was developed based on a Gaussian process and Genetic algorithm approach.

Overview of the Framework

Key points:

- ❖ A 'one-click' automated workflow to give feedback for consolidated part quality and mould design optimisation;
- ❖ Virtual Layup ➡ Virtual Autoclave ➡ Virtual inspection ➡ Mould optimization;
- ❖ A robust, fast and high-fidelity approach;
- ❖ Homogeneous modelling approach - 1000 times faster - lays the base for optimization [1];
- ❖ High fidelity material model in consolidation/cure simulation [2].

Research object : Industry semi-complex part in CAD format
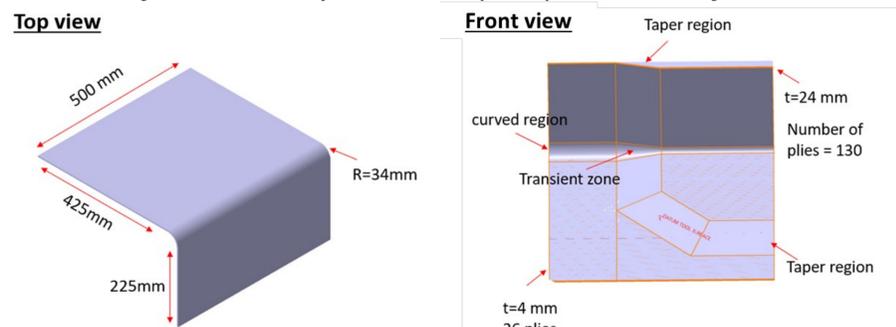
Schematic of the composite part studied in this work top view (left) and front view(right).

Virtual Layup: from as-designed geometry to as-layup FE model

Workflow for Virtual Layup.

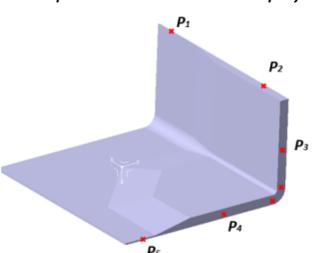*Virtual Autoclave: Fast and robust consolidation process simulation*
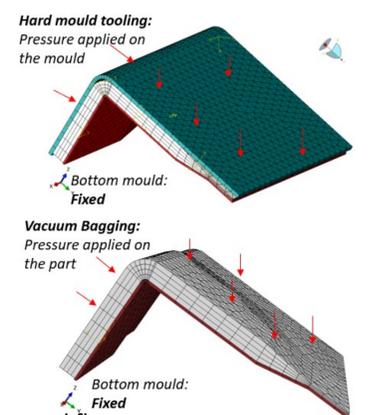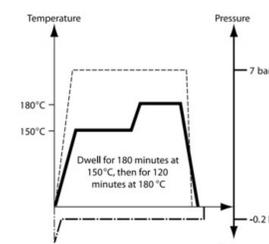
Virtual Autoclave workflow.
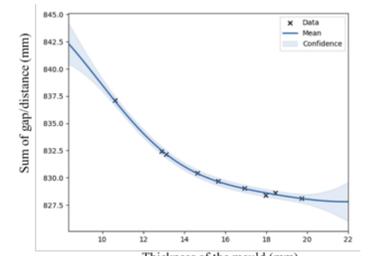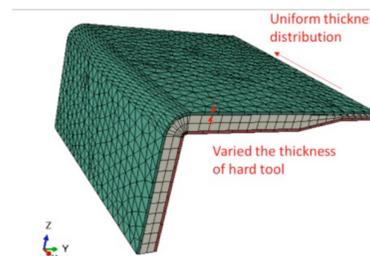
Experimental Validation
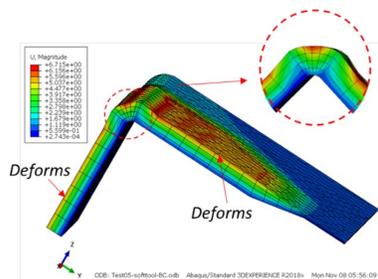
*Comparison between the physical part and model prediction in defects generation.*

Position	Measured (mm)	Predicted (mm)	Error(%)
P1	4.29	4.07	-5.13
P2	23.90	23.93	0.13
P3	23.89	23.98	0.38
P4	23.71	24.03	1.35
P5	4.37	4.07	-6.94

Comparison between the physical part and model prediction in part thickness.

Machine Learning-based Optimisation

Tool thickness optimisation using Gaussian process emulator (uniform thickness).
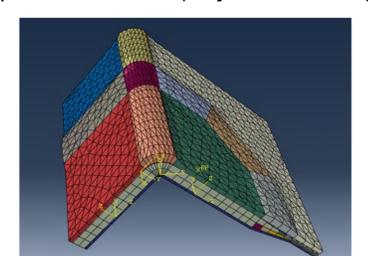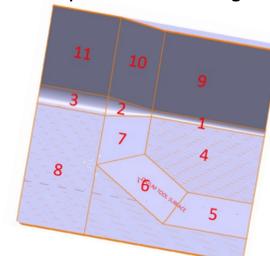
Optimisation of multi-section tool thickness.

[1] Belnoue, J.P.H. and Hallett, S.R., 2020. A rapid multi-scale design tool for the prediction of wrinkle defect formation in composite components. *Materials & Design*, 187, p.108388.
[2] Belnoue, J.H., Nixon-Pearson, O.J., Ivanov, D. and Hallett, S.R., 2016. A novel hyper-viscoelastic model for consolidation of toughened prepregs under processing conditions. *Mechanics of Materials*, 97, pp.118-134.

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NATIONAL COMPOSITES CENTRE

Autonomous and objective characterisation of composite precursors in manufacturing

Anatoly Koptelov, Jonathan Belnoue, Ioannis Georgilas, Stephen Hallett, Dmitry Ivanov.

The research was focused on the application of a novel adaptive consolidation sensor framework for the characterisation of composite precursors. The designed framework develops material driven test programmes in real-time and defines robust material models for the studied composite precursor. The proposed approach allows to remove any subjective judgement about the material behaviour and to reduce human involvement at the experimentation stage. The proposed framework along with the developed data transfer/acquisition hardware setup was put to the test within several characterisation exercises. The output of the proposed testing method—model and properties for the tested materials—is compared with the results of the conventional deterministic characterisation tests.
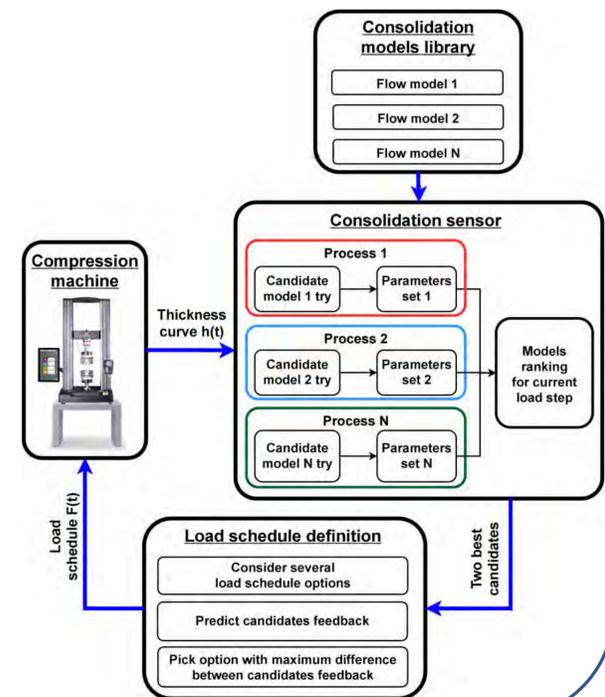
Autonomous real-time testing setup

The adaptive testing framework is located on the host (PC/laptop) and connected to the compaction rig throughout data acquisition hardware
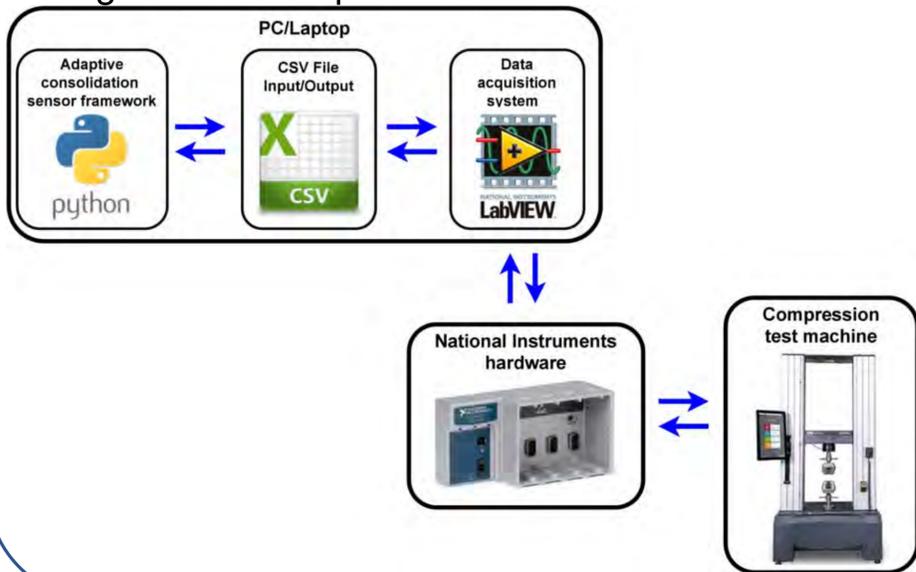
Detailed algorithm of the framework

The main purpose of the ATF is to build a testing programme in real time and in a responsive manner based on the continuously supplied data on thickness evolution of a tested sample. After the end of each load step, the framework challenges all models from the library (candidate models) to analyse the incoming compaction response from the testing machine.

Compaction rig setup

- Default 25 kN load cell
- Hydraulic grip
- Temperature controlled compression platens
- 1 kN cantilever beam load cell
- Angle plate fixture
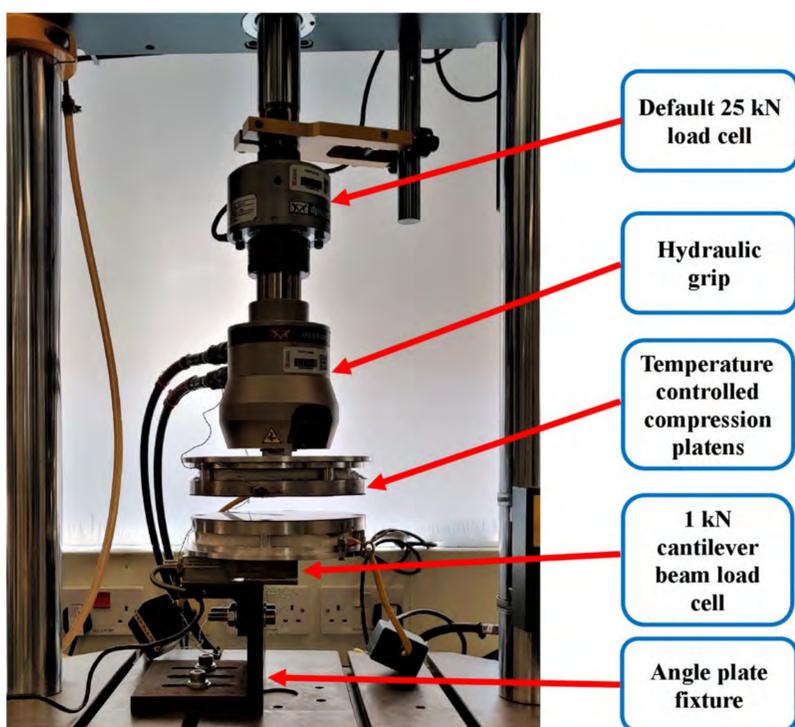
Real-time material testing

Resulting loading programmes and compaction curves for the real-time experimentation. Upon the completion of each test, the framework successfully identified the best performing material models and the corresponding set of material parameters. Overall, the autonomous testing demonstrated strong potential for objective assessment of complex material systems and clear direction for further development.
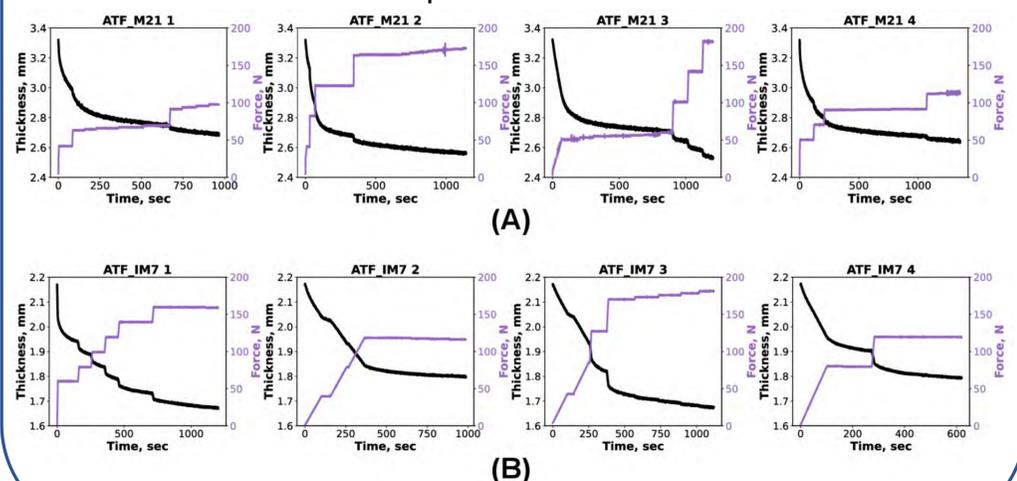
(A) IMA/M21 prepreg, (B) IM7/8552 prepreg.

HypoDrape: Continuum based textile model for simulating forming processes

Adam Thompson, Jonathan Belnoue, Stephen Hallett

HypoDrape is a user material subroutine for Abaqus Explicit that includes the kinematic behaviour of the fibrous tows in biaxial textiles to ensure the stresses are resolved correctly. This enables key behaviours of to be included within forming simulations of textiles, resulting in accurate predictions of deformations and defects.

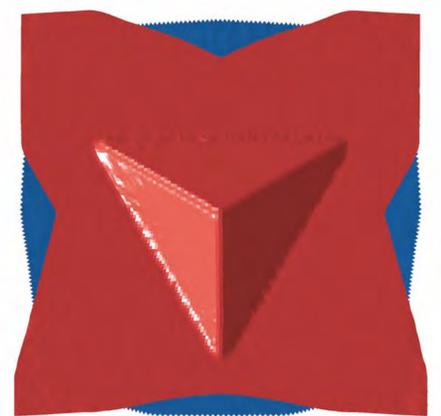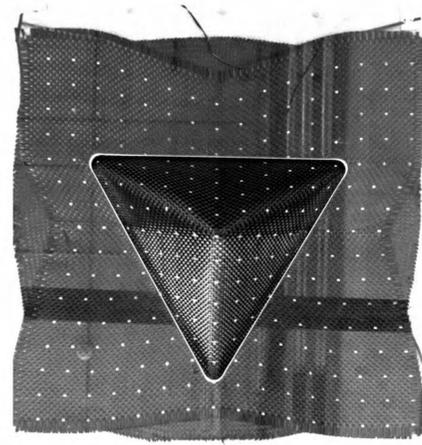The subroutine is distributed freely from the Bristol Composites Institute Github page: https://bristolcompositesinstitute.github.io/HypoDrape/
It is being actively used by both the National Composites Centre and Airbus and has led to international collaborations with the University of British Columbia and Aalborg University.

Comparison of multi-layer forming experiments with simulation for blank holder forming processes
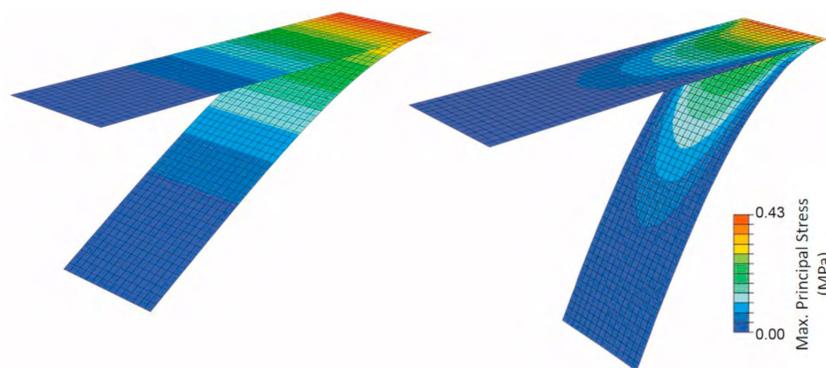
Effect of fibre orientation on bending deflection (stiffness) [0/90] (left) and [±45°] (right)
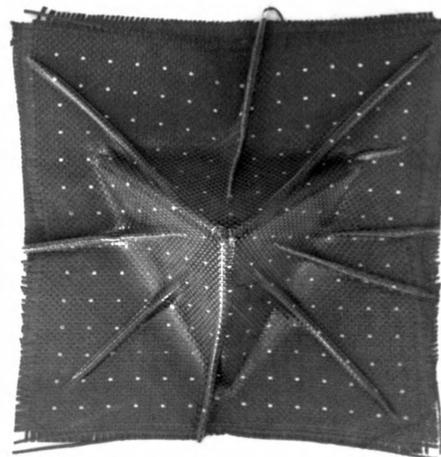
Comparison of multi-layer forming experiments with simulation for Double Diaphragm forming processes
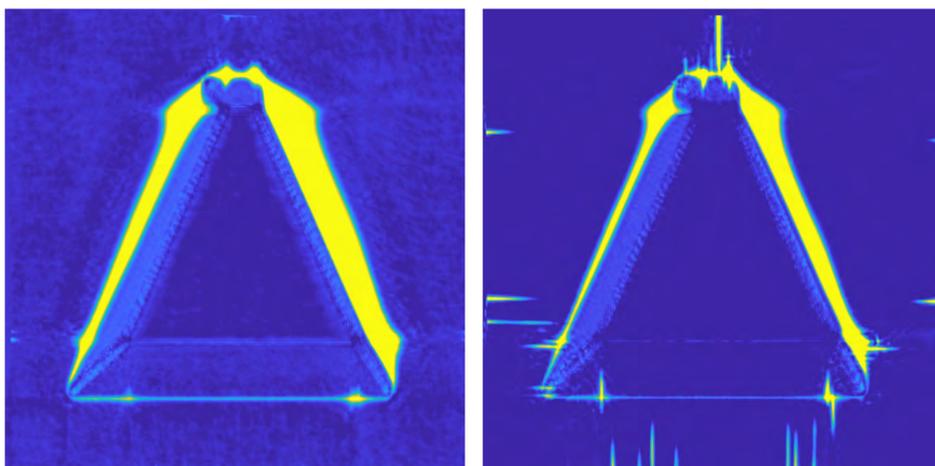
Gradient plot showing the variation of thickness after forming (left) and after consolidation (right) of 18 plies of a pre-preg textile

Recent developments Include:

- extension to pre-impregnated textiles, capturing the inter-ply interactions and through-thickness consolidation behaviour

- introduction of non-linear bending stiffness to improve the accuracy of wrinkle shape and size

- use for optimisation of forming processes through external constraints and local stiffening of the preform.

Model based optimisation of an induction coil for improved macro-scale temperature uniformity

James Uzzell, Laura Pickard, Ian Hamerton, Dmitry Ivanov

Electromagnetic (EM) induction has great potential in energy efficient manufacturing as it provides rapid, volumetric and localised heating. Heat is induced directly within electrically conductive carbon fibres reducing thermal losses to tooling and producing high heating rates.

Application of induction to composites is challenging due to (a) non-uniform magnetic field of conventional coil, (b) low electrical and thermal conductivity of CFRP. Sequentially coupled magnetic and transient thermal modelling has been used to optimise the heating process through (i) parametric design of induction coil, (ii) engineering material architecture.
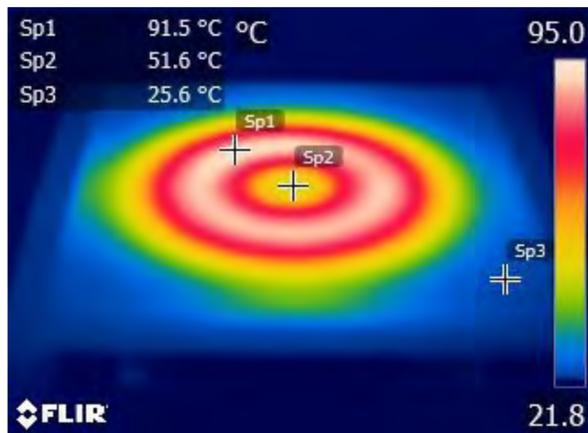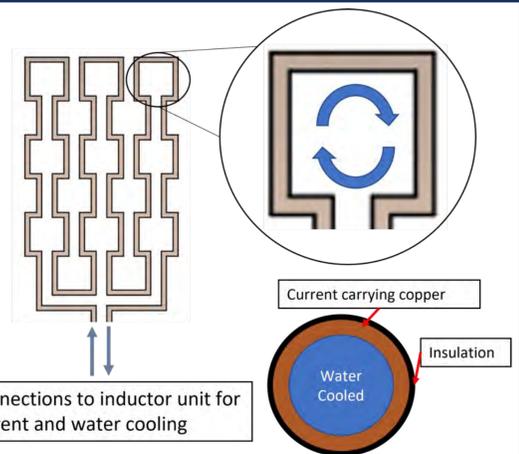
Challenge:

Sp1 91.5 °C
Sp2 51.6 °C
Sp3 25.6 °C
°C 95.0
21.8

Above: (Left) Photograph showing standard pancake coil design used for metallic processing. (Right) Thermal image showing the ring shaped heating pattern produced using the pancake coil.

Modelling Workflow:

EM Input parameters:
• Geometry
• Electrical conductivity
• Magnetic permeability

Thermal input parameters:
• Thermal conductivity
• Heat capacity
• Density

EM model and analysis

Joule heating distribution

Temperature distribution

Transient heat transfer model

Model calibration:

Comparison of temperature in carbon fibre laminate between experimental pancake coil and model.

Right: Comparison of cooling rate in lab verses using the applied surface convective film conduction in the model.

Research Hypothesis:

To reduce characteristic heat propagation length, a cellular coil structure has been trialled. Each cell forms isolated EM vortices if the process parameters are properly tuned. Each EM vortices imprints a pattern of Eddy currents and Joule heating.

Coil manufactured approx. A4 size (350mm x 200mm).

Connections to inductor unit for current and water cooling

Current carrying copper

Water Cooled

Insulation

Process design:

61.0 °C
20.0 °C
42.0 °C
21.0 °C
59.0 °C
22.0 °C

Above: (Top) Experimental temperature variation with different QI carbon fibre panel sizes. (Bottom) Modelling results for same sized panels.

Parametric design optimisation:
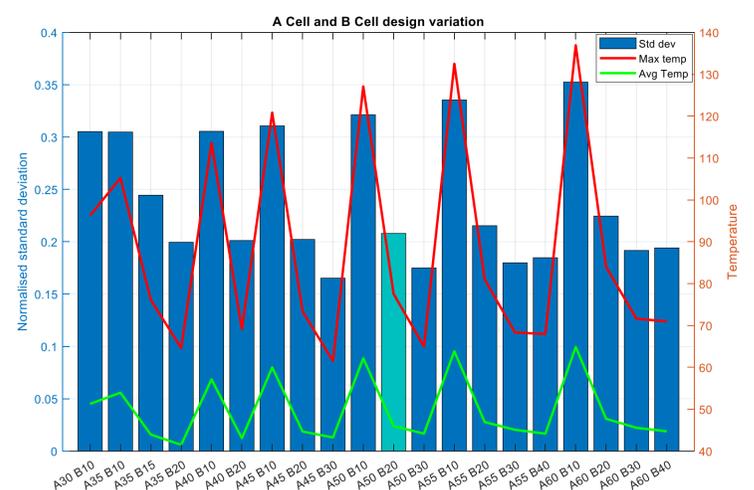
Above: Graph showing parametric design varying size and spacing of each cell. Focusing on reducing standard deviation to improve inplane temperature uniformity and maximising average temperature for heating efficiency. Light blue bar indicates current experimentally tested geometry

Tensile Characterisation of HiPerDiF PLA/Short Carbon Fibre Tape Under Processing Conditions with Micromechanical Model

Burak Ogun Yavuz, Ian Hamerton, Marco Longana and Jonathan Belnoue

Aim: Material characterisation for forming simulations of aligned discontinuous fibre thermoplastic (HiPerDiF) prepreg by using micromechanical model

Manufacturing Method

1

Impregnation

- Vacuum Bag
- Breather
- Peel Ply
- PLA Tape
- HiPerDiF Preform
- Male Mould
- Female Mould
- Vacuum Mould
- Vacuum Port
- Sealant

@ 195 °C
Under Vacuum Pressure For 4 Hours

One batch of production

Specimen

35 mm DIC Region
Tab Region — Fiber Direction — Tab Region
75 mm
5 mm

Cross section

Fibre Volume fraction ≈ 35%

Tensile Characterisation under Processing Conditions

2

Test setup

- @ 20 °C, 80 °C, 100 °C, 120 °C, and 140 °C
- @ 1mm/min, 10mm/min, 100mm/min crosshead speeds
- Shimadzu electromechanical test machine
- Thermal Chamber
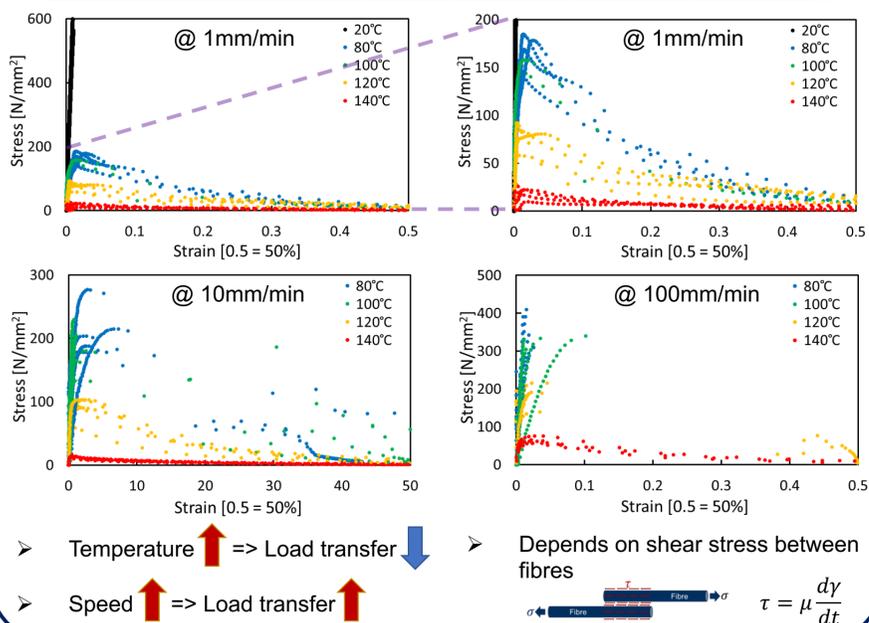- 10 kN load-cell
- 5MP Stereo DIC
- Strong LED light source

Tensile behaviour temperature and speed dependency

@ 1mm/min (20°C, 80°C, 100°C, 120°C, 140°C)

@ 1mm/min (20°C, 80°C, 100°C, 120°C, 140°C)

@ 10mm/min (80°C, 100°C, 120°C, 140°C)

@ 100mm/min (80°C, 100°C, 120°C, 140°C)

Stress [N/mm²], Strain [0.5 = 50%]

➤ Temperature ⬆ => Load transfer ⬇

➤ Speed ⬆ => Load transfer ⬆

➤ Depends on shear stress between fibres

$$\tau = \mu \frac{d\gamma}{dt}$$

Rheology and DSC of PLA

3

Rheology test setup

- 170 °C contact temperature
- Oscillations
- From 1 rad/s to 628 rad/s
- @ 80 °C, 100 °C, 120 °C, 140 °C
- 0.5mm thickness

Temperature history

Temperature [°C] vs Time
Low crystallinity
High crystallinity

Viscosities with two different temperature history

Low crystallinity — 80°C, 100°C, 120°C, 140°C
Viscosity [Pa.S] vs Speed [Rad/s]

High crystallinity — 80°C, 100°C, 120°C, 140°C
Viscosity [Pa.S] vs Speed [Rad/s]

➤ Corresponding viscosity of high crystallinity PLA has less temperature dependence

Differential scanning calorimetry (DSC)

- 1°C/min ramp rate
- 20°C>190°C>20°C>190°C>20°C>110°C>20°C>190°C
- PLA and PLA/Carbon fibre
- ➤ Low temperature crystallization is stronger than recrystallization and ends about 100 °C
- ➤ Annealing up to 110 °C creates high level of crystallinity

DSC /(mW/mg) [3] ↑ exo, Temp. /°C, Time /min

Micromechanical Model

4

- Shear rate dependent storage modulus ($G(\dot{\gamma})$) and corresponding viscosity ($\eta(\dot{\gamma})$) data taken from rheology experiment with high crystallinity
- Fibre length (L)=3mm, Diameter (D)=7µm, Fibre volume fraction (f)=0.35, Overlap length (δ)=1.5mm, Fiber volume fraction parameter (K)=2.64

$$\dot{\sigma} = \left(2G(\dot{\varepsilon})\left(\frac{L-\delta}{D}[K-1]f\frac{\delta}{D}\right)\dot{\varepsilon} - \left(\frac{G(\dot{\varepsilon})}{\eta(\dot{\varepsilon})}\right)\sigma\right)$$

Micromechanical model

$$\sigma = 2\tau f \frac{\delta}{D}$$
Shear stress to Tensile stress

$$\tau + \frac{\eta}{G}\dot{\tau} = \eta\dot{\gamma}$$
Maxwell viscoelastic model

$$\dot{\gamma} = \frac{L-\delta}{D}[K-1]\dot{\varepsilon}$$
Shear strain to Tensile strain

80 C° 1mm/min — calculated, real
Stress [N/mm²] vs Strain [0.5 = 50%]

80 C° 10mm/min — calculated, real
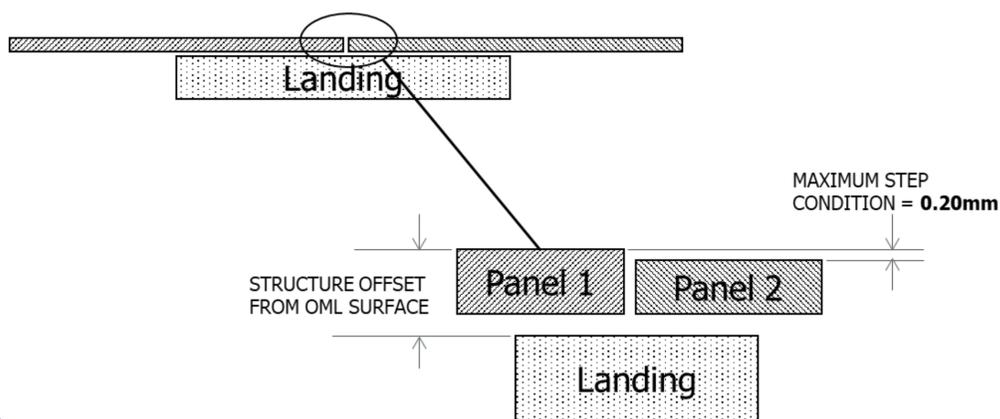Stress [N/mm²] vs Strain [0.5 = 50%]

Future work: Implementing material behaviour into forming simulations → Forming defect free parts experimentally

Laminate Thickness Control

Kate Gongadze, Chris Dighton, Martin Moss, Brett Hemingway, Jonathan Belnoue, Stephen Hallett

When manufacturing composite laminates, the cured ply thickness can vary by as much as 5%. In order to achieve the required laminate thickness, compensation plies are co-cured or co-bonded onto the laminate and machined back. This procedure is lengthy and therefore costly to include in the manufacturing phase. Consequently, this manufacturing procedure could be further optimised by modelling and simulating the process, taking into account the material and process variabilities.
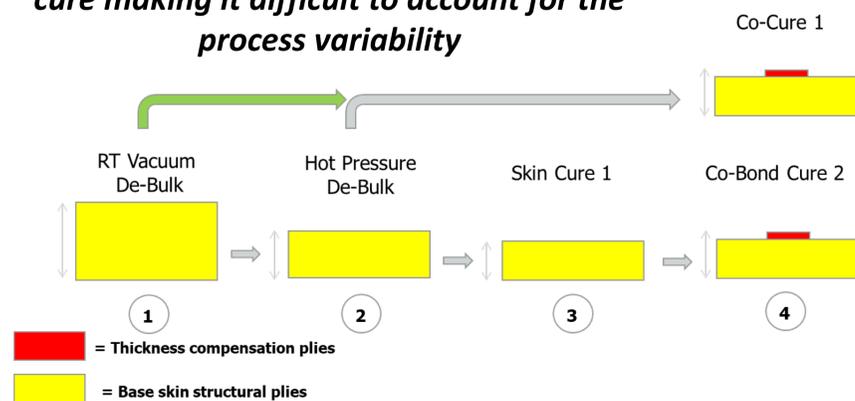
The Challenge

Landing

MAXIMUM STEP CONDITION = **0.20mm**

STRUCTURE OFFSET FROM OML SURFACE

Panel 1   Panel 2

Landing

Material Variability

Uncured material with variability in thickness, volume fraction, resin content
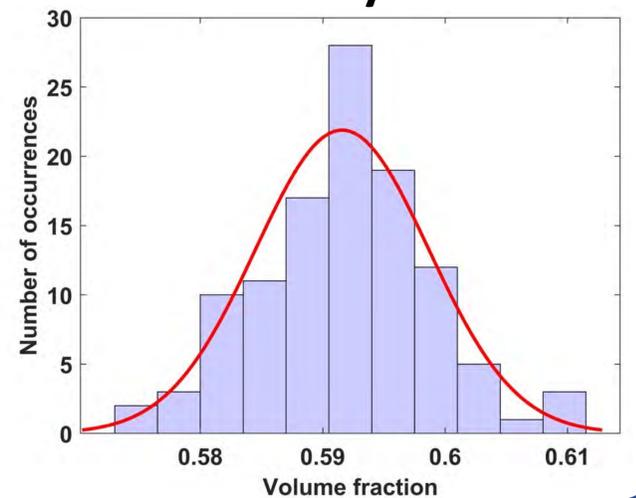
Process Variability

The laminate goes through several stages of cure making it difficult to account for the process variability
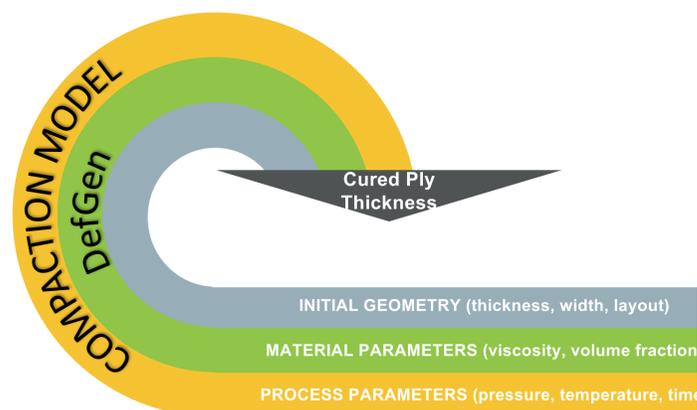

Co-Cure 1

RT Vacuum De-Bulk   Hot Pressure De-Bulk   Skin Cure 1   Co-Bond Cure 2

① ② ③ ④

■ = Thickness compensation plies

■ = Base skin structural plies

Validation

LTC – Measurement Data Acquisition

CFC laminate vacuum consolidated to granite flat bed

Black Static Intercept Vacuum Membrane (Anti Corrosion Tooling Protection as per PTS 39 shown to efficiently reflect laser light

Use of Laser Line Scanner – New Product Development Centre, 4 Shed

Unit: - Nikon Modelmaker MMDX50 - MCAx25+ Romer Arm

Green polyester Flashtape tab zones scanned to establish base datum

State-of-the-art laser line scanner provide accurate measurements of the thickness variability

Process Modelling

COMPACTION MODEL
DefGen
Cured Ply Thickness
INITIAL GEOMETRY (thickness, width, layout)
MATERIAL PARAMETERS (viscosity, volume fraction)
PROCESS PARAMETERS (pressure, temperature, time)

Predicted cured ply thickness
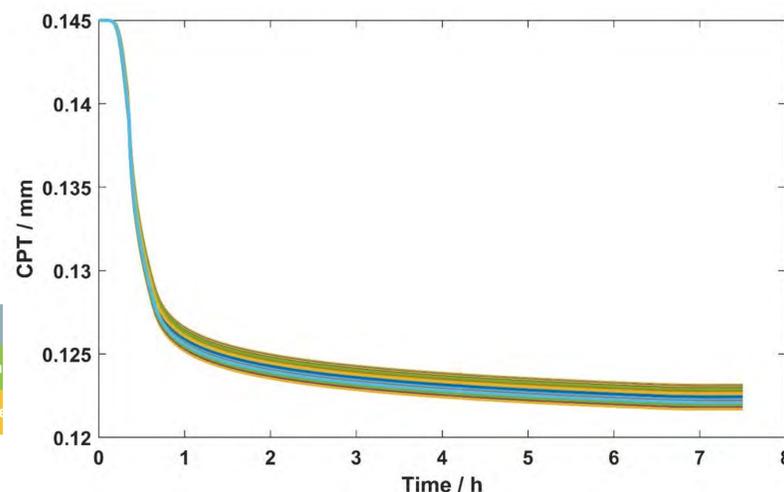
Conclusions

Cured ply thickness (CPT) remains a challenge, especially when tight tolerances are required. Combining process modelling with material and process variability could prove to be an invaluable tool.

University of BRISTOL

Bristol Composites Institute

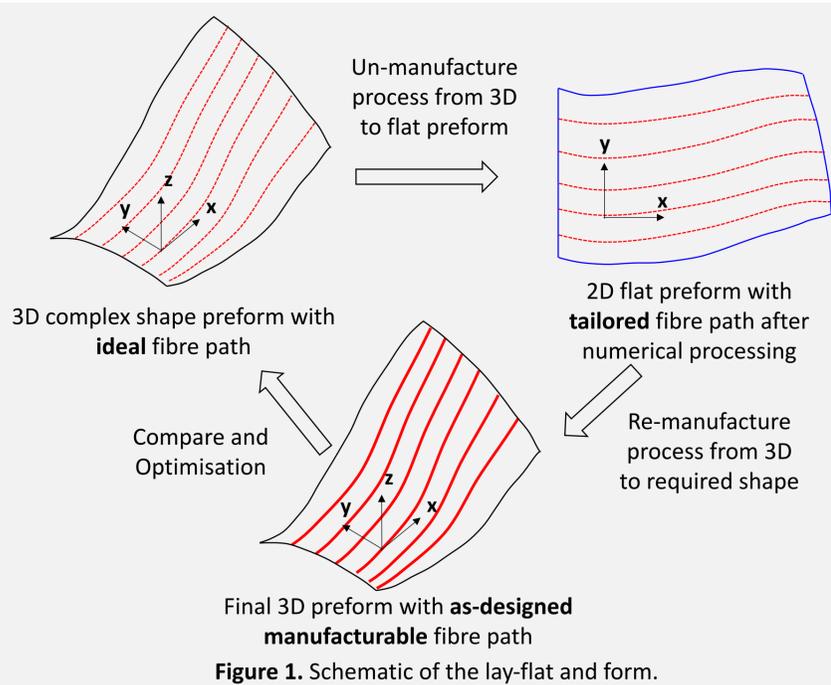UK RI Engineering and Physical Sciences Research Council

SIMprocs

Virtual Un-manufacturing of Fibre-steered Preforms for Complex Geometry Composites

Xiaochuan(Ric) Sun, Wei-Ting Wang, Jonathan Belnoue, ByungChul(Eric) Kim, Stephen Hallett

Automated Fibre Placement (AFP) technology is ideally suited to manufacture structures with simple geometry due to its robustness, speed and repeatability. However AFP is not well-adapted for directly laying up complex 3D shapes as the geometry and need for defect free manufacture constrain the head speed, making manufacture time consuming and thus costly. In most cases, complex geometry composites components are designed based on ideal or theoretical fibre angles, with little or no consideration of the manufacturing processes or constraints involved in delivering them.

This study took a novel virtual approach to "un-manufacture" these ideal designs for the case of formed composites, so that flat tailored preforms can be created via the continuous tow shearing (CTS) technique, which results in the required ideal fibre architectures after forming (see Fig. 1). The primary manufacturing process envisaged to deliver this is the diaphragm forming of thermoset prepregs deposited using automated deposition. However, it is anticipated that the concept developed will be applicable to textile preforms (including non-crimp fabrics) and thermoplastic prepregs. The objectives of this project is to demonstrate the proof of concept and feasibility of the proposed manufacture processes and to develop numerical tools needed, along with experimental validation.

Work Flow

Un-manufacture process from 3D to flat preform

3D complex shape preform with **ideal** fibre path

2D flat preform with **tailored** fibre path after numerical processing

Re-manufacture process from 3D to required shape

Compare and Optimisation

Final 3D preform with **as-designed manufacturable** fibre path

Figure 1. Schematic of the lay-flat and form.

Methodology

Figure 2. experimental results (left) of forming using UD prepreg with marked grids and model prediction (right) for the re-forming of prepreg tailored fibre path
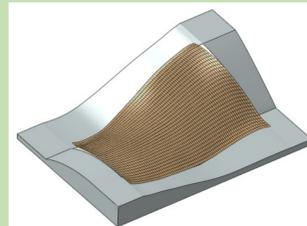
Figure 3. Wide tape CTS machine steering a 100 mm wide unidirectional prepreg tape.

Work packages:

WP1. Numerical modelling of forming and un-forming of steered fibres prepreg stacks on representative complex 3D shape

WP2. Experimental characterisation of prepreg in-plane properties

WP3. Manufacture of technology demonstrator and quality inspection
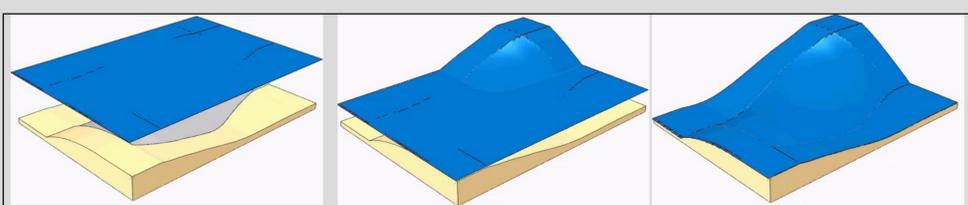
Numerical Results

Figure 4. Numerical process modelling of double diaphragm forming (note the part in blue is diaphragm)
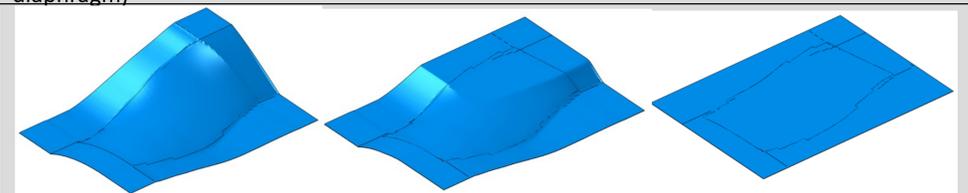

Figure 5. Numerical process modelling of double diaphragm un-forming (note the part in blue is diaphragm, prepreg model is sandwiched between two diaphragm parts)

- Two processes were fully reversible
- 2D flat prepreg with tailored fibre path after post-processing was obtained.
- Fibre path was extracted from prepreg model and passed to manufacture CTS tapes
- 2D flat prepreg model was then put back to forming simulation, the result of which is compared with the ideal fibre path to form a complete optimisation cycle
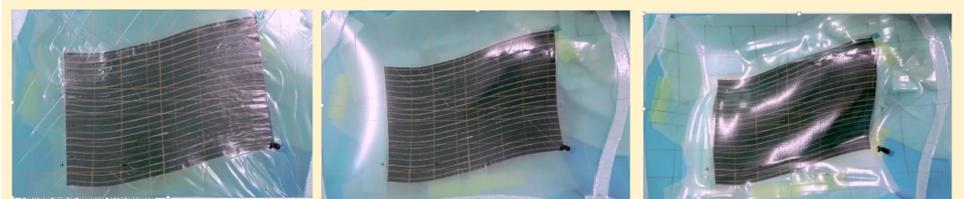
Experimental Results

Figure 6. Double diaphragm forming test on tailored CTS prepreg where fibre path was derived from un-forming simulation

Figure 7. Comparison between Formed tailored CTS prepreg and Reformed preform with tailored fibre path

- Steered fibre tape was made using CTS technique with fibre trajectory derived numerically
- Reformed steered prepreg was found to be similar to modelling results.

- Validated numerical and experimental results demonstrated the feasibility of the proposed manufacture processes which can have lower cost and greater efficiency compared to direct AFP on complex shape
- Steered fibre paths on demonstrator was found to have less wastage and more continuous fibre across the whole part

# Springback During Cyclic Compressive Loading of Carbon/Epoxy Prepregs

Iryna Tretiak, Anatoly Koptelov, Jonathan Belnoue, Dmitry Ivanov, Stephen Hallett

During AFP processing, the deposited material undergoes cyclic mechanical loading and unloading induced by sequential passes of the compaction roller. The behaviour of the material under cyclic compaction becomes much more complex for material systems where hysteresis and permanent strain are an issue. Previous studies have also documented a springback effect in dry fibres, and it is expected that the springback effect in other material systems will differ and result in further complexities.
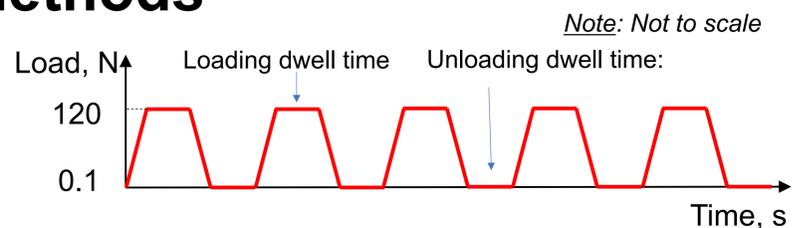
In this work, an investigation of the mechanical response to cyclic compressive loadings of toughened carbon/epoxy prepregs is undertaken. The experimental outcomes were used for further development of an existing state-of-the-art phenomenological material model. The acquired experimental data sets new requirements for the model to include a springback response during load relaxation and provides information for extensive validation.

Materials and Methods

Hexcel® **IM7/8552** (nominal CPT 0.125 mm)
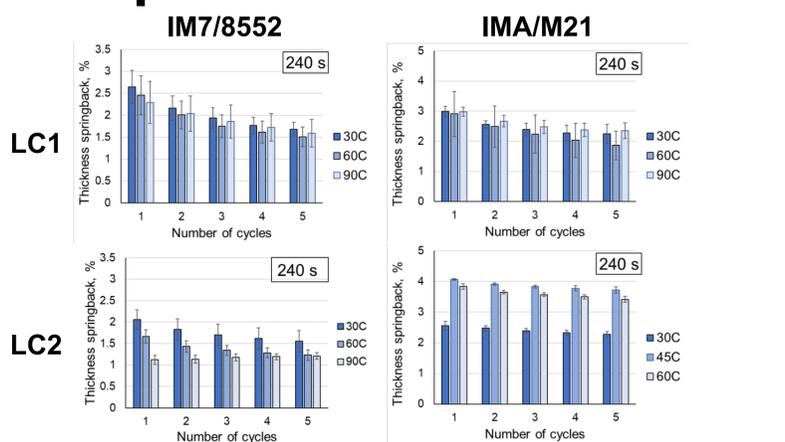Hexcel® **IMA/M21** (nominal CPT 0.184 mm)

16 plies
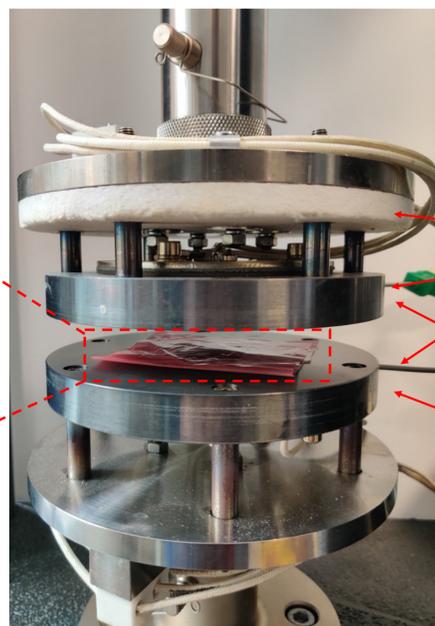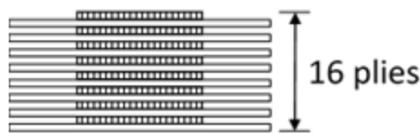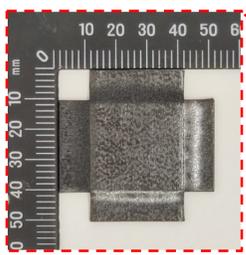
Insulation
Top plate
Thermocouples
Bottom plate

Note: Not to scale

Load, N
Loading dwell time
Unloading dwell time:
120
0.1
Time, s

Loading case	Loading dwell time, s	Unloading dwell time, s	Compaction temperature, °C
1 – simulates debulking process	240	120; 240; 360; 480	30, 60, 90
2 – simulates AFP process	6	120; 240; 360; 480	30; 60; 90 for IM7/8552 30; 45; 60 for IMA/M21

Loading/unloading rate - 45 N/s

Experimental Results

IM7/8552   IMA/M21

LC1 — 240 s — 30C, 60C, 90C
LC2 — 240 s — 30C, 45C/60C, 90C/60C
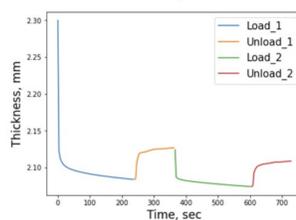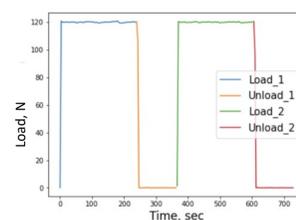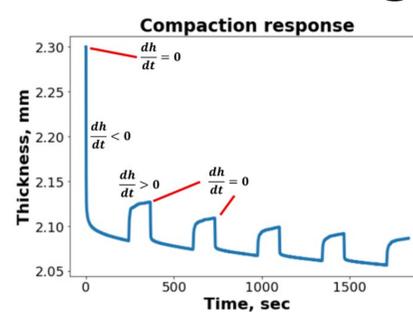
Number of cycles — Thickness springback, %

- Springback tends to decrease with each successive cycle
- Higher springback value is different based on material type, loading schedule and dwell time (all these parameters influence compaction level)

Cycle 1, Cycle 2, Cycle 3, Cycle 4, Cycle 5
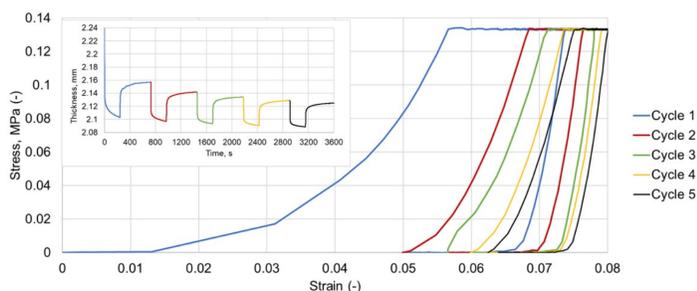
Stress –strain curves shows highly non-linear and visco-plastic behaviour. The area of the hysteresis loop initially decreases and then reaches the equilibrium

Modelling Approach

Compaction response

$\frac{dh}{dt} = 0$

$\frac{dh}{dt} < 0$

$\frac{dh}{dt} > 0$

$\frac{dh}{dt} = 0$

Material model

$$\frac{dh(t)}{dt} = Q(t) * P(t)$$

Gutowski Model

$$P_{pre}(f) = \sigma_A \frac{\sqrt{f/f_0} - 1}{\left(\sqrt{f_{lim}/f} - 1\right)^4}$$
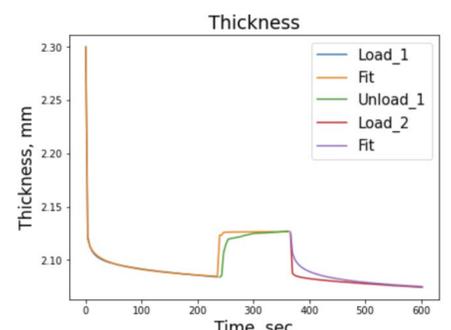
Split the compaction response for loading and unloading sequences

Loading
$$\frac{dh(t)}{dt} = Q(t) * P(t)$$

Unloading
$$\frac{dh(t)}{dt} = Q(t) * (-P_{pre})$$

Thickness — Load_1, Fit, Unload_1, Load_2, Fit

Load_1, Unload_1, Load_2, Unload_2

Pros:
- Easy to use
- Can isolate parameters
- Original model is intact

Cons:
- Springback response is not active during loading

Multi-scale modelling of woven composites accounting for shear: experimental validation
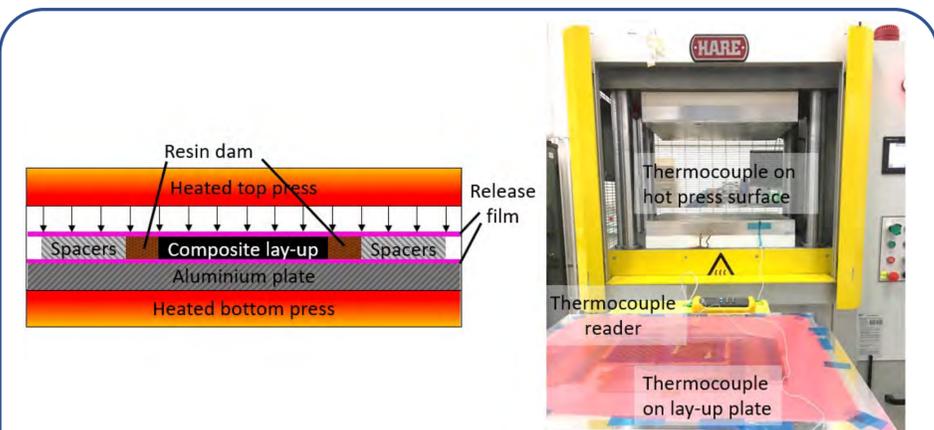
Meng yi Song, Adam Thompson, Bassam El-Said and Stephen Hallett

Shear occurs when a 2D textile is formed over a 3D geometry with double curvature. During shear, the warp and weft tows rotate away from their orthogonal axes, changing the anisotropy of the material. This is carried through the consolidation process and is locked into the cured composite component. An experimental campaign was carried out to will validate the response from the multi-scale modelling framework. The material used is a 2x2 twill woven prepreg. Composite plates are manufactured, coupons are cut and are subject to tensile tests with DIC.
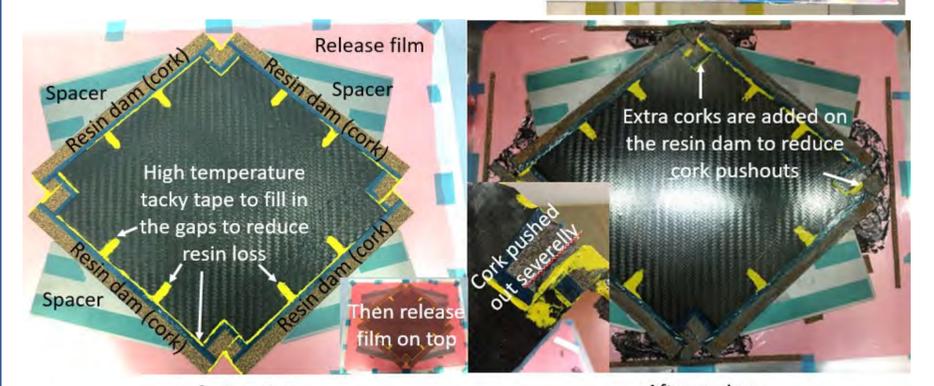
1. Cut prepreg.
2. Picture frame sitting on a mounting rig.
3. Peel backing paper off the prepreg flanges and assemble clamping arms.
4. Tighten all screws.
5. A tightened screw.
6. Bring picture frame to tensile machine. Remove locking bar and shear.
7. Once achieved desired shear angle, put back locking bar. Bring back to clean room and remove the ply.
8. Debulk every two plies for total of 6 plies per composite plate.

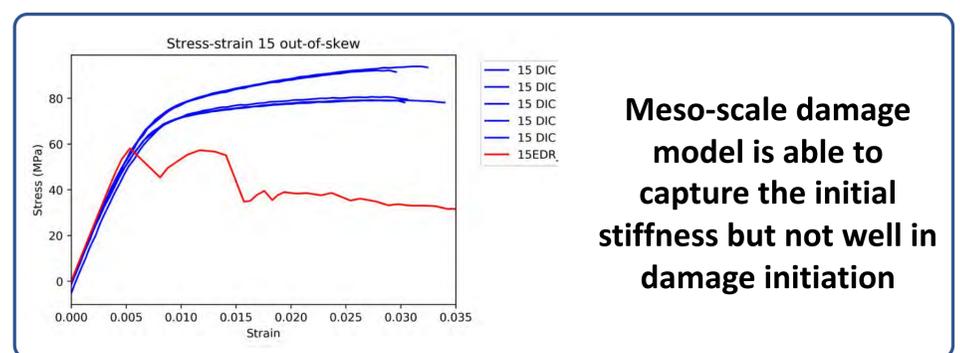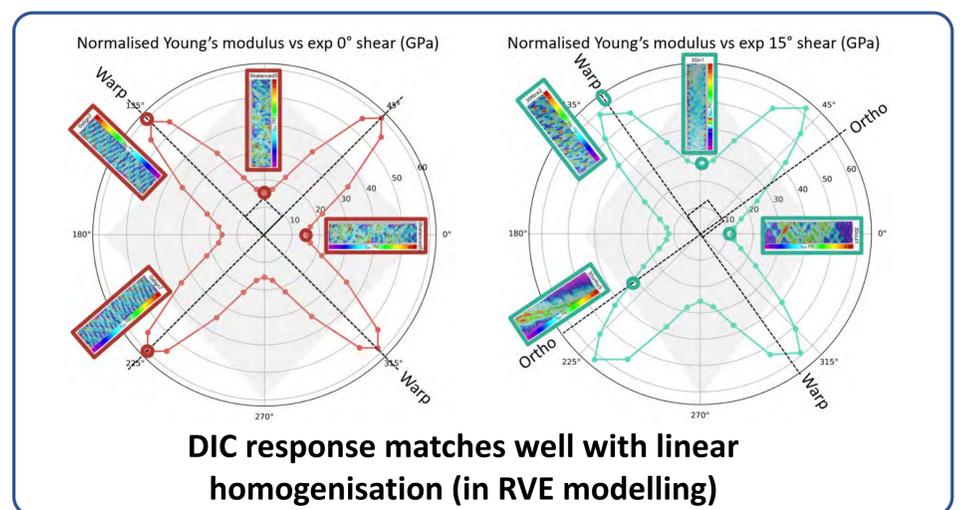**Shear individual plies using picture frame and debulking**

Cure the composite using a hot press

Normalised Young's modulus vs exp 0° shear (GPa)

Normalised Young's modulus vs exp 15° shear (GPa)

DIC response matches well with linear homogenisation (in RVE modelling)

Stress-strain 15 out-of-skew

15 DIC
15 DIC
15 DIC
15 DIC
15 DIC
15EDR

Meso-scale damage model is able to capture the initial stiffness but not well in damage initiation
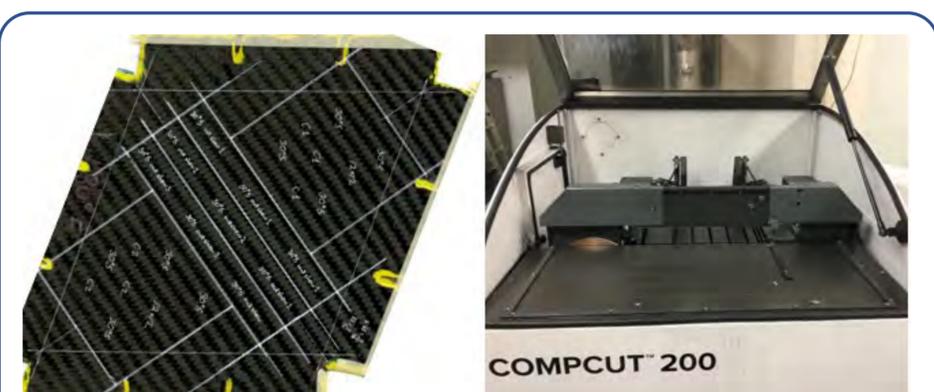
Coupons are drawn on the cured plate and then sent to the workshop for cutting

Failure patterns for 15° shear in +-45° tensile test configuration compared with DIC
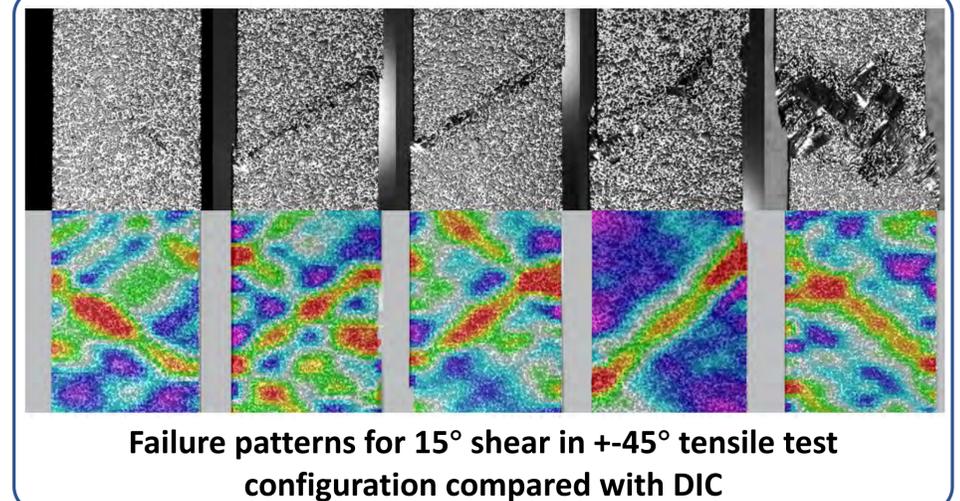
Multi-scale modelling of woven composites accounting for shear

Meng yi Song, Adam Thompson, Bassam El-Said and Stephen Hallett

Shear occurs when a 2D textile is formed over a 3D geometry with double curvature. During shear, the warp and weft tows rotate away from their orthogonal axes, changing the anisotropy of the material. This is carried through the consolidation process and is locked into the cured composite component. This workflow focuses on finding the mechanical properties of the sheared woven composite materials; and the application of these properties into macro-scale simulations.
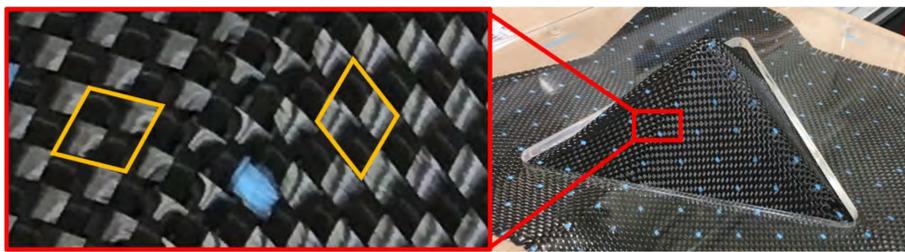
Shear arises when a 2D fabric is formed over a 3D shape with double curvature

Micro scale: filament   Meso scale: tow/unit cell   Macro scale: shell

Geom input   Geom input

Levels of objectivity: This workflow focuses on the meso-scale RVE and the macro-sale shell model

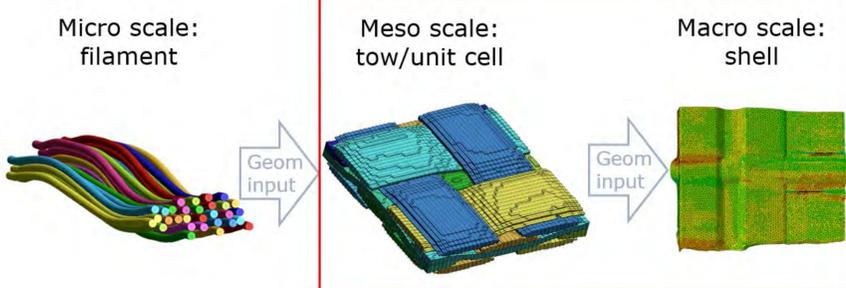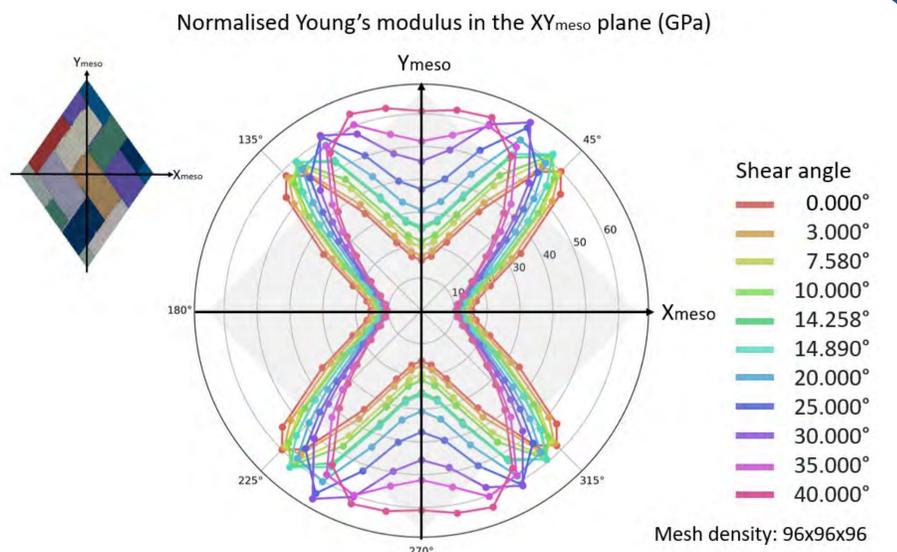Generated voxel mesh   Mapped tows   Tow orientations

Create a series of RVE models for a range of shear angles informed by the forming simulation.

Normalised Young's modulus in the XY_meso plane (GPa)

Shear angle
- 0.000°
- 3.000°
- 7.580°
- 10.000°
- 14.258°
- 14.890°
- 20.000°
- 25.000°
- 30.000°
- 35.000°
- 40.000°

Mesh density: 96x96x96

Homogenise the solution for each RVE model to obtain engineering constants such as Young's modulus. Or to plot a stress-strain graph

Fabric - unconstrained
Upper tool - encastre
Frame - encastre
Lower tool - displacement in +Z
Frame - encastre
Fabric - unconstrained
Upper tool - encastre
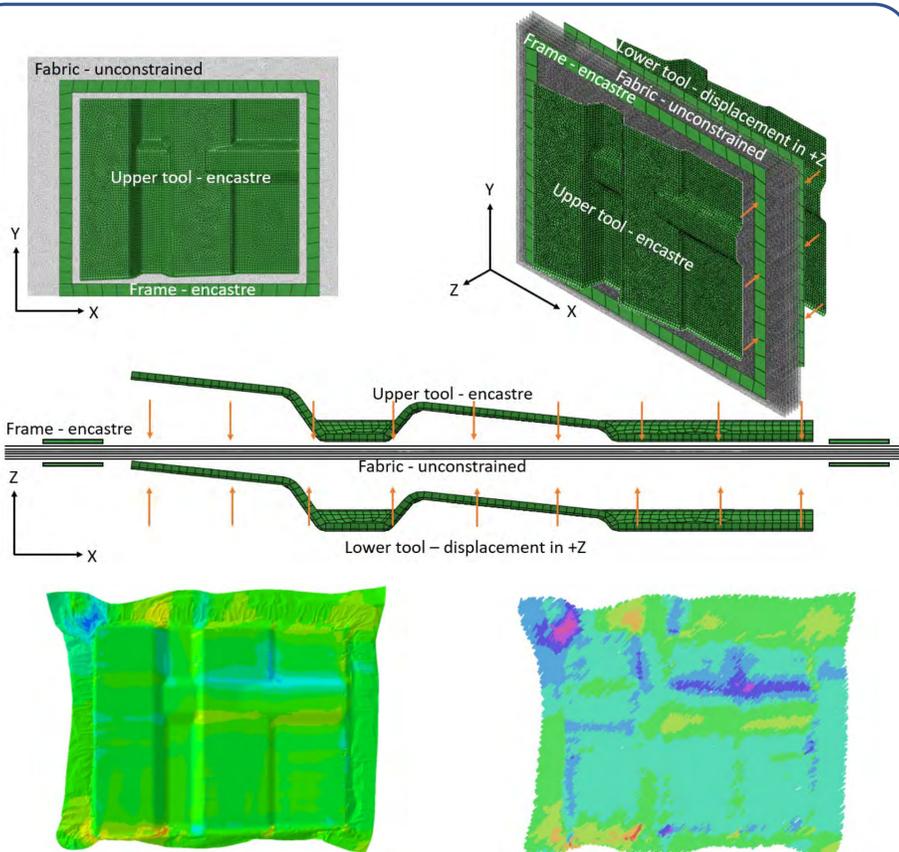
Perform a forming simulation to obtain shear angle distribution and RVE rotation

Forward load: with shear
S, Max. In-Plane Principal
MERGED_PART-1-LIN-6-1 (top)
+9.434e-02
+8.401e-02
+7.369e-02
+6.336e-02
+5.304e-02
+4.271e-02
+3.239e-02
+2.206e-02
+1.174e-02
+1.414e-03
-8.911e-03
-1.924e-02

Vibration mode 4: with shear

Forw load: without shear

Vibration mode 4: without shear
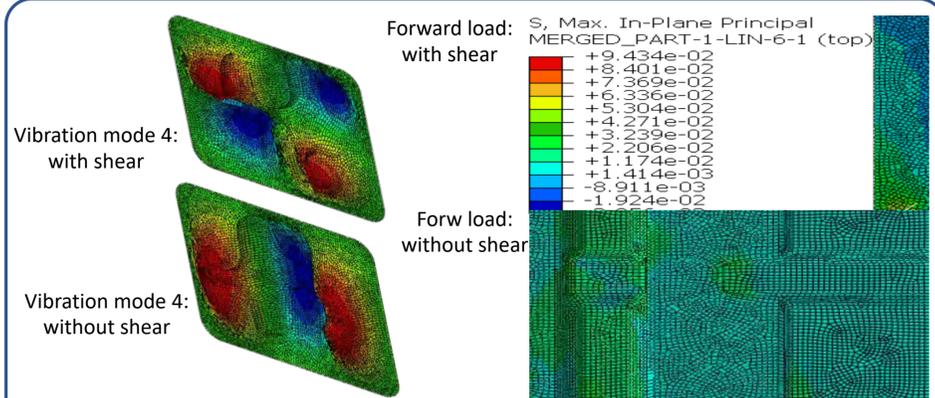
The macro-scale shell model has their element assigned with their respective material and orientation based on the shear angle, RVE rotation and the homogenised RVE properties.

Understanding pre-preg tack performance under varied processing conditions

Yi Wang, Jonathan Belnoue, Dmitry Ivanov, Stephen Hallett

Prepreg tack is a critical material property that plays a key role in Automated Fibre Placement (AFP) manufacture-induced defect generation. However, there is a gap in current state-of-the-art manufacturing process modelling that includes tack phenomena and experimental data that shows the influence of multiple factors. A modified probe test method, which is capable of inter-ply and ply-tool tack measurement, is proposed. The influence of multiple factors, consistent with the AFP deposition process (i.e. pull-off rate, contact time, pressure and temperature) on tack is studied. Further, a comprehensive modelling framework accounting for all the factors is developed and implemented as a user subroutine for a commercial finite element (FE) package. The work highlights the complexity of tack behaviour at play and shows promise for filling the gap between the tack data/model scarcity and simulation of manufacturing processes such as AFP and forming.

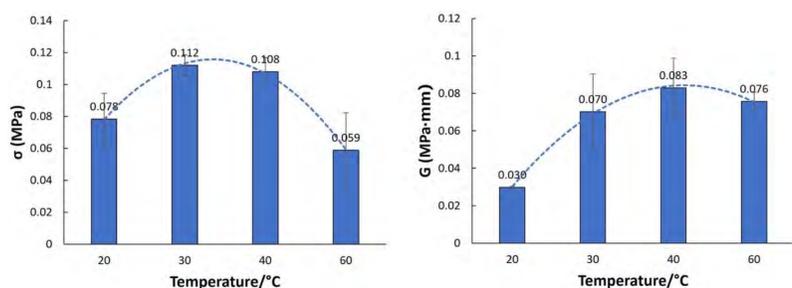## Prepreg tack's role in AFP deposition
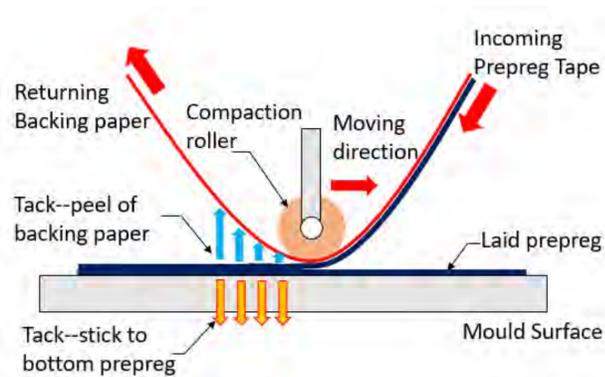
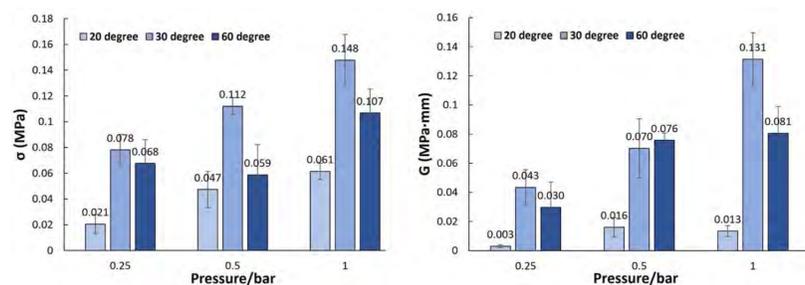## Modified probe test capable for Inter-ply prepreg tack measurement
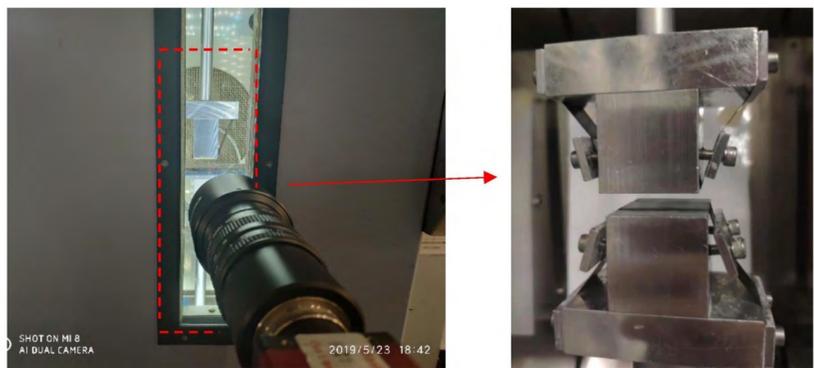
Test design and tack characterisation

Temperature	Prepreg-to-prepreg									Tool–to-prepreg
	Deformation rates & Contact time			Pressure			Ply orientation			Contact type
Selection	1 mm/s 30s	6 mm/s 6s	16 mm/s 2s	0.25bar	0.5bar	1bar	0°|0°	0°/45°	0°/90°	Prepreg|Alum
20°C	✓		✓	✓	✓	✓				
30°C	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
40°C		✓								
60°C	✓	✓	✓	✓	✓	✓				

A comprehensive modelling framework for tack behaviour prediction

Varied processing conditions are included:
1/ Temperature,
2/ Layup speed,
3/ Contact time,
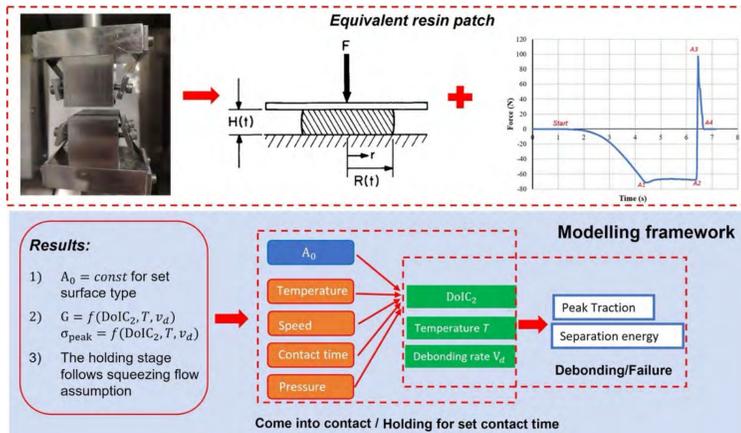4/ Compaction,
5/ Debonding rate.

Test results

Influence of temperature on the peak stress (left) and the separation energy (right).

Influence of temperature on the peak stress (left) and the separation energy (right).

Implementation of the modeling framework for AFP simulation
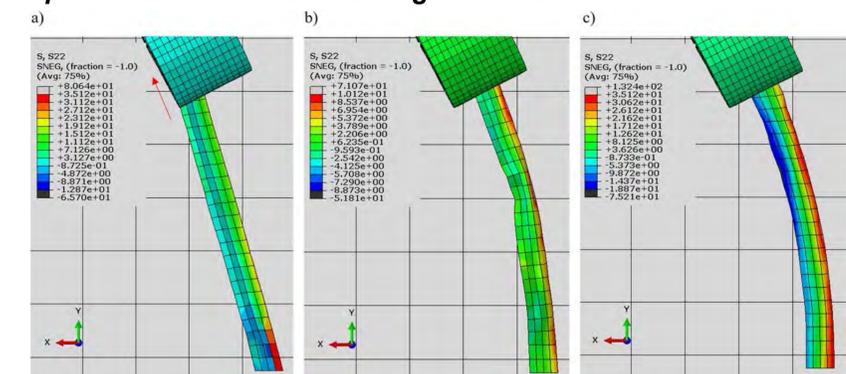
Influence of tack property on deposition results a) hard contact without tack definition, b) tack definition with prepreg-to-tool condition, c) tack definition with prepreg-to-prepreg condition.

Conclusions:

- The modified probe tack test provides a feasible approach to measure the prepreg tack between adjacent layers of prepreg
- The experimental study reveals the strong and non-monotonic dependence of the tack properties on temperature, pressure level and contact time.
- A full modelling framework was proposed and is capable to show the tack role in AFP process
- The test approach and modeling framework can be extended to other manufacture processes that use uncured prepreg, such as forming

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Reference: Wang, Y., Mahapatra, S., Belnoue, J.P.H., Ivanov, D.S. and Hallett, S.R., 2023. Understanding tack behaviour during prepreg-based composites' processing. Composites Part A: Applied Science and Manufacturing, 164, p.107284.

New experiments for in-plane shear characterisation of uncured prepreg

Yi Wang, Dmitry Ivanov, Jonathan Belnoue, James Kratz, Stephen Hallett

Automated Fibre Placement (AFP) is becoming one of the mainstream composites manufacturing techniques in commercial aerospace. However, one of the limitations is the occurrence of the defects generated in the tow steering process, e.g. wrinkles and tow pull off. Defect formation is closely related to the in- and out of plane properties of uncured prepreg. This work focuses on the in-plane shear behaviour characterization of thermoset prepreg by a unidirectional off-axis tensile test, taking into account the layup speed and tow width, to better understand and further simulate the AFP process.

Zoom in of 1,250mm
Defect
Woven ply surface
Steered tows
1,250mm
1,350mm
1,500mm
2,000mm
Compressible wrinkles
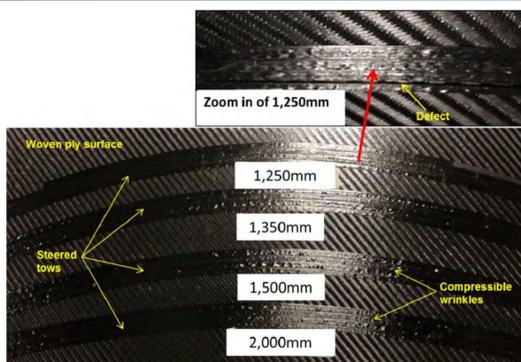
Defects generated in AFP steering process [1]
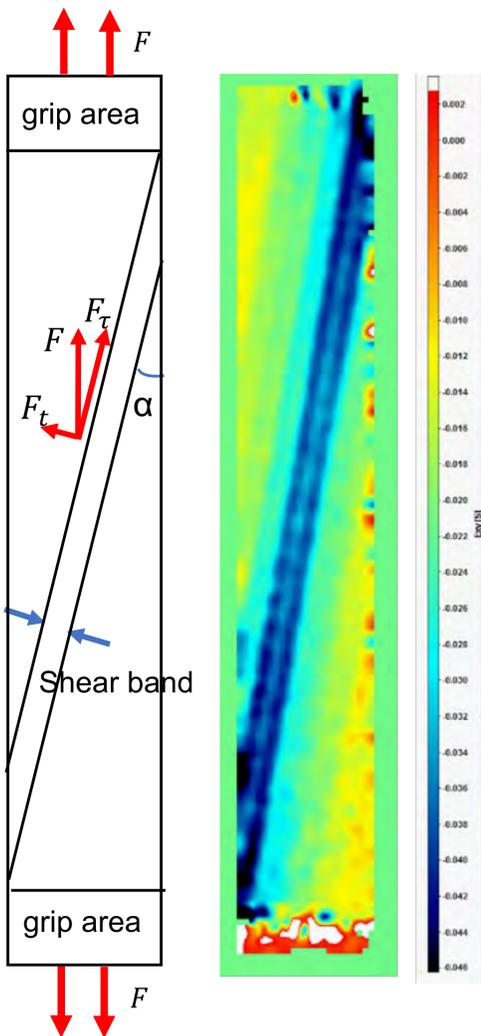
Related to:

- In-plane behaviour (**shear**/bending)
- Surface characteristics (tack, friction)

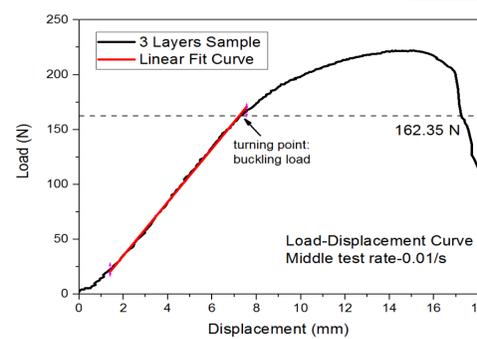## In-plane shear characterisation

- ❖ Method: 10˚ off-axis tensile test
- ❖ *Hexcel* IM7-8552 carbon/epoxy prepreg
- ❖ Shear strain extraction by DIC analysis results
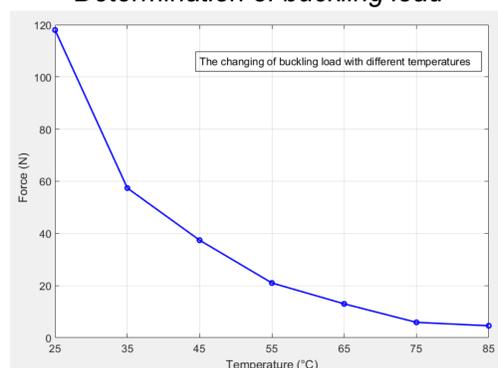- ❖ Resolving local stress state for shear stress

DIC analysis results:

F
grip area
F_τ
F
F_t
α
Shear band
grip area
F

Shear strain field

Test results in room temperature

3 Layers Sample
Linear Fit Curve
162.35 N
turning point: buckling load
Load-Displacement Curve
Middle test rate-0.01/s
Load (N)
Displacement (mm)

Determination of buckling load

The shear stress vs strain curves with different thicknesses
5 Layers
3 Layers
4 Layers
Shear stress (Mpa)
Shear strain (%)
3 layers
4 layers
5 layers

Stress/Strain curves with different layers

Temperature influence investigation

The changing of buckling load with different temperatures
Force (N)
Temperature (°C)

Evolution of buckling load with temperature

The shear stress-strain curves under different temperatures with test rate-0.001/s
Shear stress (MPa)
Shear strain (%)
25°C
50°C
75°C
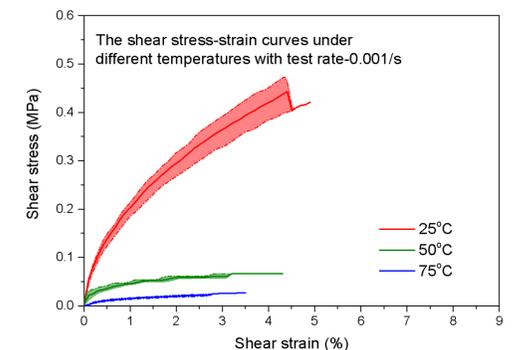
The shear stress-strain curves under 0.001/s

The shear stress-strain curves under different temperatures with test rate-0.01/s
Shear stress (MPa)
Shear strain (%)
25°C
50°C
75°C
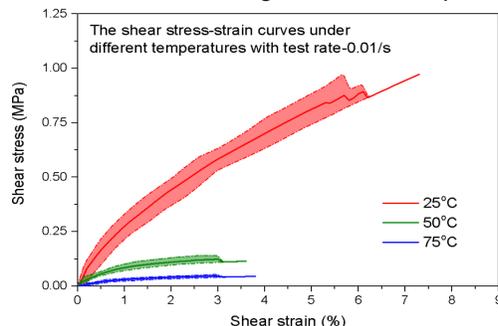
The shear stress-strain curves under 0.01/s

The shear stress-strain curves under different temperatures with test rate-0.1/s
Shear stress (MPa)
Shear strain (%)
25°C
50°C
75°C
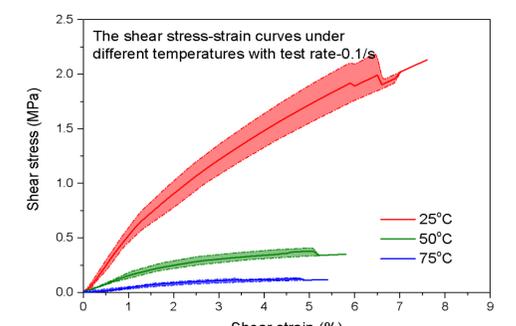
The shear stress-strain curves under 0.1/s

Conclusions:

- This test allows extraction of the non-linear in-plane shear stress/strain relationship of uncured prepreg;
- The shear behaviour of uncured prepreg does not vary much with different thickness specimens;
- The stiffness of the material is heavily dependent on the test rates and temperatures.

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Reference: Wang, Y., Chea, M.K., Belnoue, J.P.H., Kratz, J., Ivanov, D.S. and Hallett, S.R., 2020. Experimental characterisation of the in-plane shear behaviour of UD thermoset prepregs under processing conditions. Composites Part A: Applied Science and Manufacturing, 133, p.105865.

Fast Optimisation of the Formability of Dry Fabric Preforms: a Bayesian Approach

Siyuan Chen, Adam Thompson, Tim Dodwell (Exeter University), Stephen Hallett and Jonathan Belnoue

Composites are becoming increasingly important for light-weight solutions in the transport and energy sectors. In the field of composites manufacture, resin transform moulding (RTM) is a cheaper alternative to traditional manufacturing method. Before resin infusion, the fabric is to be formed into shape, however, the quality of forming is highly sensitive to wrinkles. These defects could induce considerable reduction to the quality of final parts. Simulation is a good way to understand the process and help to investigate the effect of the forming parameters (such as pressure and tensile forces) to wrinkle generation. Current BCI's forming process simulation tool can make high quality predictions but have long run times. On the other hand, we need large batches of simulations to find the forming conditions that minimise defects.

The project aims at exploring a new framework for the efficient optimisation of the processing conditions in the dry fibre forming process. This is achieved by building a Gaussian Process (GP) emulator that is trained from finite element (FE) simulation data. The work opens the door for digital twin. Longer term, a fully autonomous forming rig that allows defect mitigation by automatic adaptation of the process based on in-situ measurements and predictions from the GP will be built.

Forming Workbench → Forming Process Simulator → Gaussian Process Emulator → Sequential Design → Fast Prediction & Optimisation
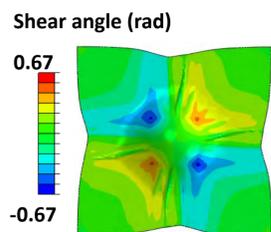
FE simulations

- Double-diaphragm forming.
- Single layer of dry NCF, hemisphere mould geometry.
- **Risers** used to provide tensions to eliminate wrinkles.
- UoB **Hypodrape subroutine**, mutually constrained membrane and shell elements, 2mm mesh.

Shear angle (rad) 0.67 / -0.67
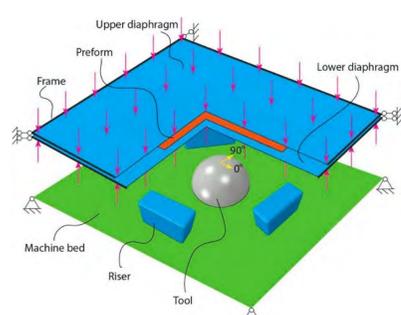
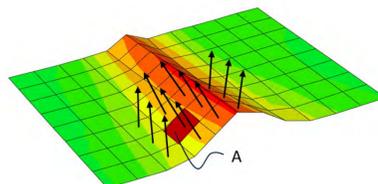**Scheme of the forming process [1]**

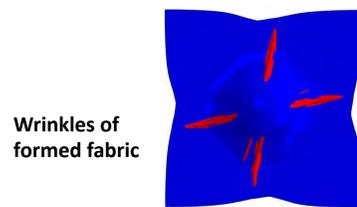**Experimental picture in [1]**

Wrinkle index (WI)

- A metric that measures the level of wrinkling near an element.
- **Sum of squared wrinkle index (SSWI)** A value that reflects the overall wrinkling level of a formed fabric.

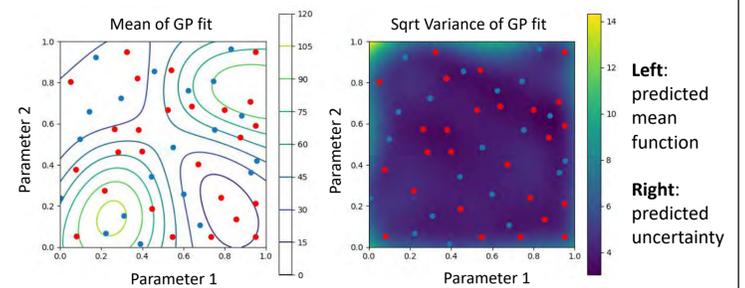WI = Variance of element normal of A and its adjacent elements

Wrinkles of formed fabric

Gaussian Process (GP) emulator

- A **machine learning method**, mathematically tracible.
- Only needs a few data points to make **accurate predictions** and **uncertainty quantification.**
- **Input:** position of four risers   **Output:** SSWI
- Each data point represents a simulation.
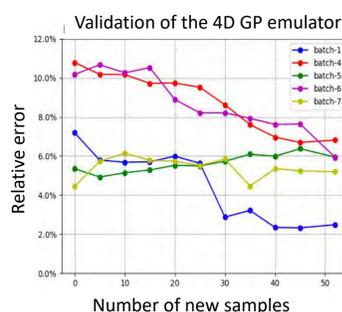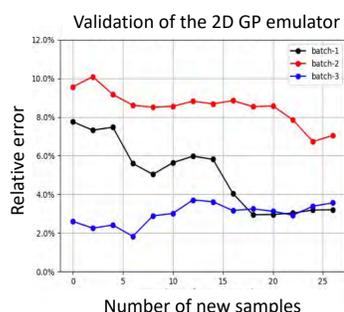
Sequential Design

- Iterative addition of supplementary data points, to improve model predictive capabilities.

Mean of GP fit — Sqrt Variance of GP fit

Parameter 2 / Parameter 1

Left: predicted mean function

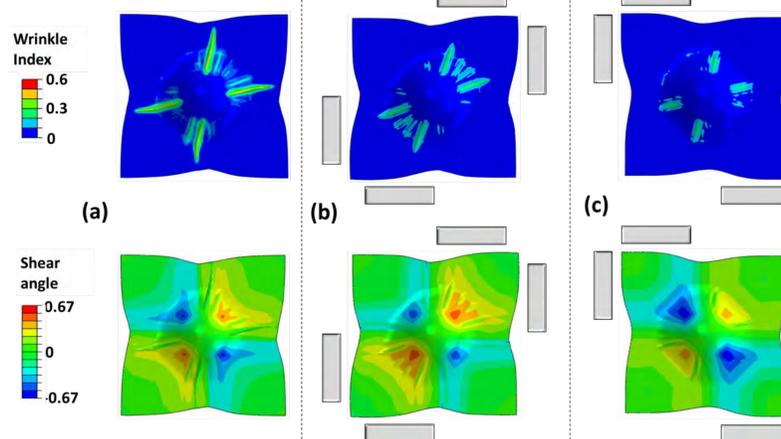**Right:** predicted uncertainty

Blue points: initial training set (20 samples), by Latin Hypercubic Sampling
Red points: supplementary training set (26 samples), by sequential design

Validation of the GPs

- A 2D GP (two parameters) and a 4D GP trained
- For most validation batches, predictive deviations reduced during sequential design. Batch 5 and 7 are good initially.
- Final predictive error is lower than 10%.

Validation of the 2D GP emulator — batch-1, batch-2, batch-3

Validation of the 4D GP emulator — batch-1, batch-4, batch-5, batch-6, batch-7

Relative error / Number of new samples

Optimisation of forming process by GP: wrinkle level significantly reduced

Wrinkle Index 0.6 / 0.3 / 0

Shear angle 0.67 / 0 / -0.67

(a) (b) (c)

(a) No-riser baseline model
Model output (SSWI) = 104
Max shear angle = 0.48
Min shear angle = -0.58

(b) Optimum found in [1]
Model output (SSWI) = 21.7
Max shear angle = 0.53
Min shear angle = -0.52

(c) Optimum in this work
Model output (SSWI) = 11.8
Max shear angle = 0.43
Min shear angle = -0.66

The blocks refer to the positions of the risers.

[1] S. Chen, O. P. L. McGregor, L. T. Harper, A. Endruweit, and N. A. Warrior, "Optimisation of local in-plane constraining forces in double diaphragm forming," Compos. Struct., vol. 201, no. January, pp. 570–581, 2018, doi: 10.1016/j.compstruct.2018.06.062
[2] S. Chen, A. Thompson, T. Dodwell, S. Hallett and J. Belnoue, Fast Optimisation of the Formability of Dry Fabric Preforms: A Bayesian Approach. Available at SSRN: https://ssrn.com/abstract=4363693 or http://dx.doi.org/10.2139/ssrn.4363693

Development of Forming Simulation Capabilities for use in Large-Scale Next-Generation Composite Aerospace Structures

Lachlan Williams, Jonathan Belnoue, Adam Thompson, Christian Knipprath (Airbus), Stephen Hallett
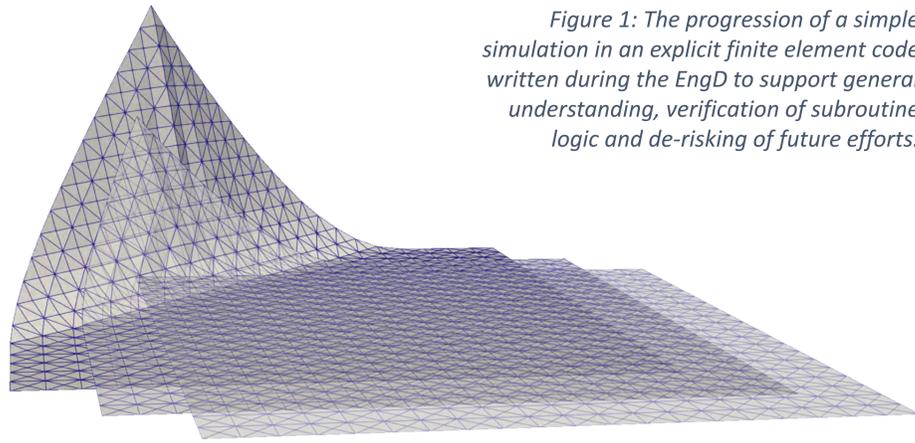

Figure 1: The progression of a simple simulation in an explicit finite element code written during the EngD to support general understanding, verification of subroutine logic and de-risking of future efforts.

Composite aerospace parts are getting bigger and more complicated. Cost pressure is driving increased part integration, which reduces overall manufacturing costs at the expense of increased forming process complexity.

High fidelity insight into forming, the process which conforms composite materials to the required geometry, and therefore dictates the all important local fibre orientation in the final part, is only increasing in importance.

How to Simulate an NCF

This research is focused on enabling competent simulation of Non-Crimp Fabric (NCF) during forming. NCF is a developing class of fibrous textiles which could be a key enabler for high rate production of composite parts in future aircraft designs. Airbus is currently evaluating NCFs in the Wing of Tomorrow programme.

Academia has gotten quite good at modelling woven textiles, but NCFs need to be modelled differently. Instead of being held together by a weave, NCFs are stitched. This stitch can behave very differently to a weave. How to accurately model the effect of the stitch on forming, without introducing excessive computational cost, is the fundamental question of this research (fig. 2).

This past year work has focused on **material model development, data handling, visualization, Finite Element (FE) fundamentals (fig. 1), software robustness and understanding the industrial digital environment.**

A Case Study in the Challenges of Digitalisation

Forming simulation is an excellent example of the challenges of adopting digital processes in an industry historically dominated by physical trials:

- Simulation does not completely remove the need for physical trials
- Availability of compatible and adaptable computational resource
- Engineering firms are more often customers than developers of software
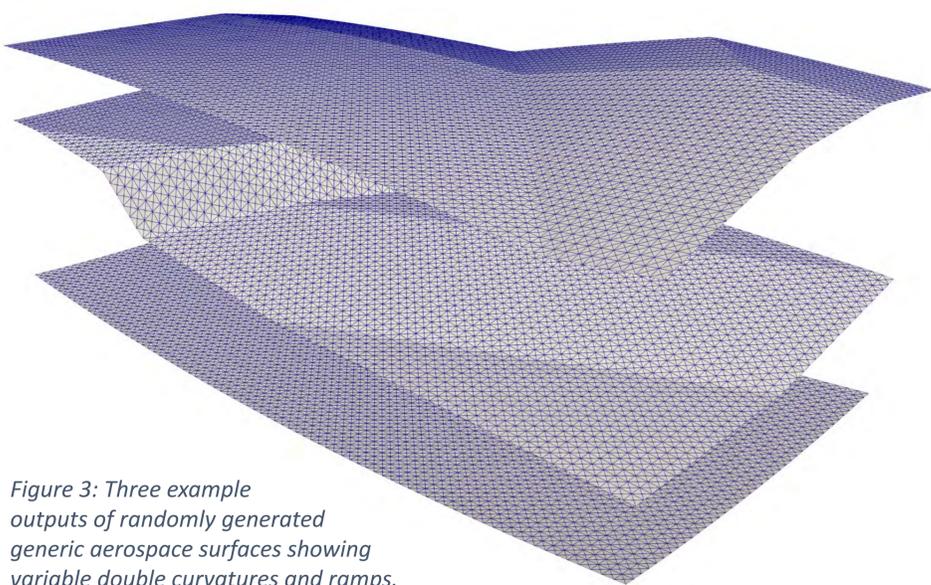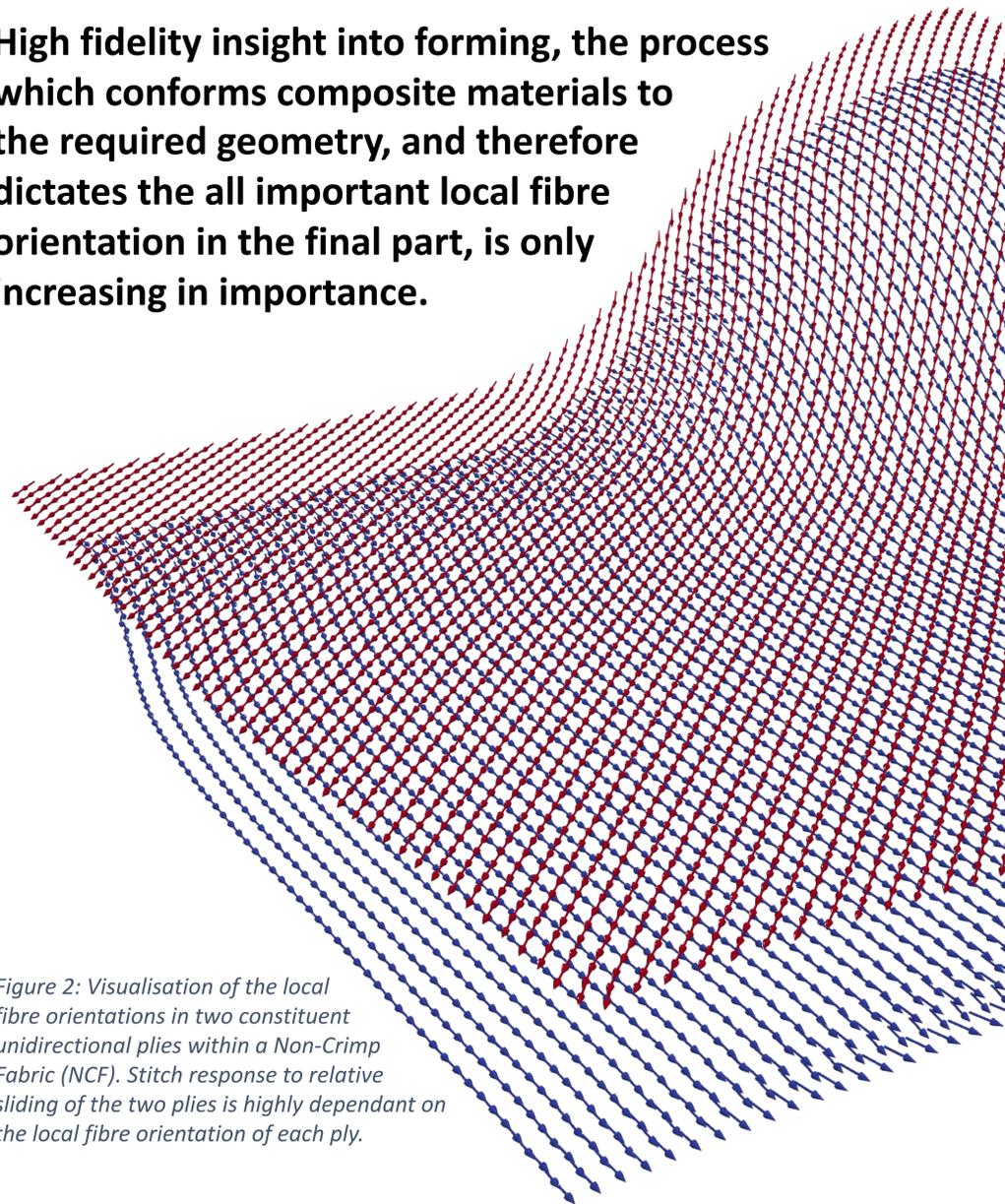- Who can communicate in both aerospace engineering and computer science?

Figure 2: Visualisation of the local fibre orientations in two constituent unidirectional plies within a Non-Crimp Fabric (NCF). Stitch response to relative sliding of the two plies is highly dependant on the local fibre orientation of each ply.

Figure 3: Three example outputs of randomly generated generic aerospace surfaces showing variable double curvatures and ramps.

Creating a Generic Aerospace Surface Generator

Model creation is often a slow, manual process. To examine the robustness of a simulation material model, ideally the model should be subjected to many representative surface geometries which capture the intended design space. Preliminary work has been done to create a forming surface generator which would facilitate this (fig. 3). This tool could be used to generate training and validation data for surrogate modelling approaches to forming simulation.

Capturing the Stitch Effect

With current and near-future computational resource available to engineers, simulating at the macro scale is here to stay. The question becomes how can we preserve some micro and meso scale physics in a computationally efficient way. Future work will explore candidate methods to realize stitch effects at the interface between constituent plies of an NCF.

Closed loop control for thermal management in manufacture

Anagnostis Samanis, Janice M. Dulieu-Barton, Jason Zheng Jiang, Dmitry S. Ivanov

This work focuses on local processes of composites manufacture under heating load aiming at optimizing the process through thermal management of temperature evolution in a controlled way of minimizing process time while avoiding any potential risk of damaging the material. The methodology finds perfect application on thermal management of thermosetting resins during infusion for local processes of repairing/bonding. The idea is the development of a heat transfer model based closed loop system which depending on temperature sensor readings is able to update the model with true values of material thermal properties and process parameters and this knowledge is exploited in a further stage by a control algorithm in a way to predict material behaviour and taking control decisions on-line to steer the temperature evolution and optimize the process.

Composite local processes

The methodology aims to offer an industrial solution to composite local processes bonding/repairing. Critical aspects of controlling the rate of heat supply and achieving temperature uniformity raise challenged to be considered.

Bonding/Joining   Repair [1]
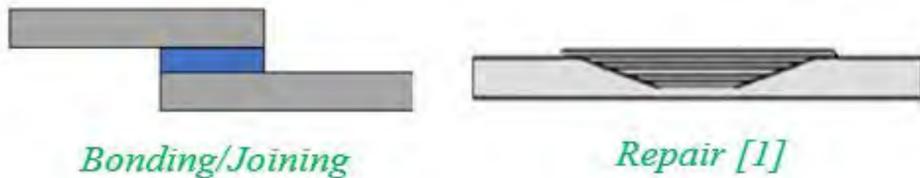
Could conventional technology offer a solution?

Conventional technology known for many years (Autoclave, Oven) ensures temperature uniformity during heating, but it applies heating to the whole structure and not locally and even to the tool making the process slow and inefficient.

[2]   [3]
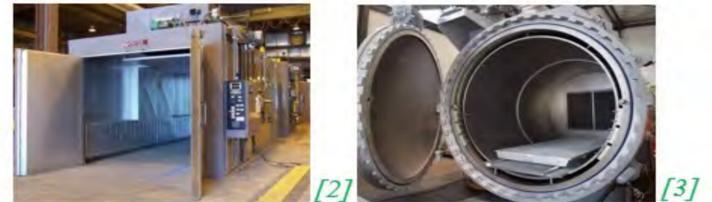
Promising heating techniques

There are some promising heating techniques offering local heating effect with fast heat supply. Though, they appear to have issues of heat sink to material/environment and non uniformity making their control quite complicated.

Flash heating [4]   Infrared heating [5]   Induction heating [1]
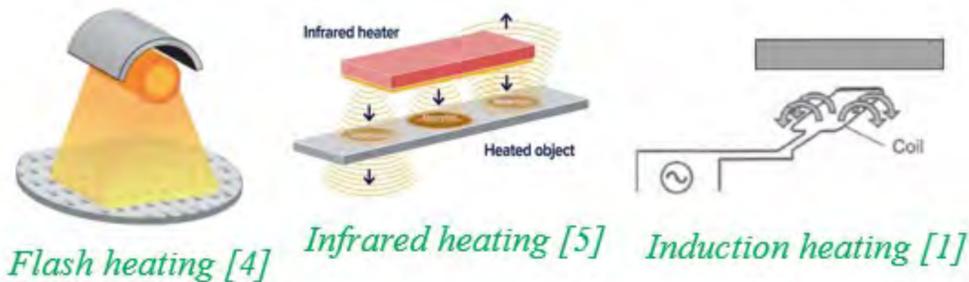
Induction heating

This work applies induction heating as a thermal source because of its ability to provide volumetric heat supply to the composite material having effect on its close surface and through thickness. Combination of induction heating with fast resin systems is a significant challenge of this study. Fast curing resins systems exhibit thermic reactions raising the risk of burning the composite. Knowing the temperature evolution everywhere in the material could eliminate that risk.

Heat transfer via Joule heating of electromagnetic materials under alternating magnetic field (coil)
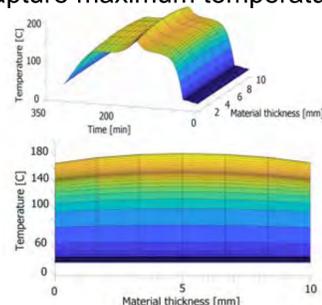
[6]
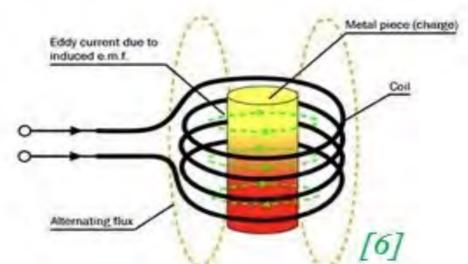
Closed loop

Closed loop system developed in the lab based on thermo-camera & thermocouples

Surface temperature

Sensor readings

Composite

Model $T(x,y,z,t)$

Coil

Power supply (AC)

Controller
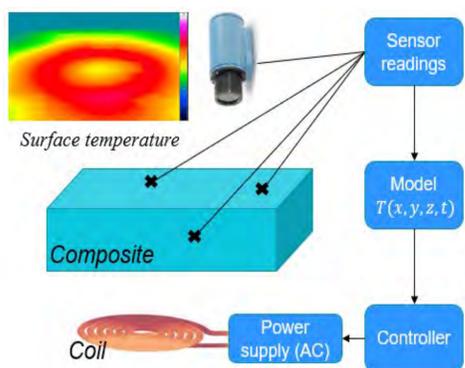
Simulation of temperature evolution

Temperature is higher through thickness. How to know in advance where to put thermo-couples to capture maximum temperature ?

A model is needed to give temperatures everywhere through calculations

Couple thermo-conduction cure kinetics & induction model

$$Q_L = Q_{cond} + Q_R + \dot{Q}_{ind}$$

Transient term — Induction heat transfer

Conduction heat transfer +(Boundaries convection)

Internal heat from [7] exothermic reactions

Model is able to provide $T(x,y,z,t)$ if we know:
- Material properties (Heat capacity / Thermal conductivity)
- Cure properties (Total heat from exotherms)
- Induction properties (Total heat transfer by inductor)
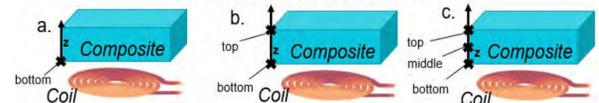- Process parameters (Heat transfer coefficient)

Identification

Identification algorithm to capture unknown thermal properties & process parameters

Multidimensional nonlinear least squares regression

Nonlinear Least squares fit
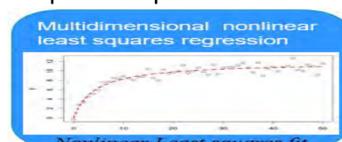
Numerical validation of black-box identification using 1D through thickness model

Identification scenario	Process time [sec]	C_p ident. error [%]	k_{zz} ident. error [%]	$h_{z,b}$ ident. error [%]	$h_{z,t}$ ident. error [%]	f_1 ident. error [%]	r_1 ident. error [%]
a. Sensor in bottom point	54.5	6.35	6.36	20.41	9.09*e+2	6.32	0.14
b. Sensor in bottom& top point	37.09	2.36	2.38	7.65	11.17	2.38	0.02
c. Sensor in bottom, middle & top point	35.17	0.17	0.18	0.57	0.84	0.17	0

Identification results in different scenarios

a. Composite / bottom / Coil
b. top / Composite / bottom / Coil
c. top / middle / Composite / bottom / Coil

Identification algorithm on unknown material

The model can achieve some physical resemblance but accuracy is not sufficient. A 2D heat transfer model is under deployment to improve accuracy

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